



# VL82C106

## PC/AT COMBO I/O CHIP

### FEATURES

- Combines the following PC/AT® Peripheral Chips:
  - VL16C450 UART - COM1:
  - VL16C450 UART - COM2:
  - Parallel Printer Port - LPT1:
  - Keyboard/Mouse Ctrl. - KBD
  - Real Time Clock
- Serial ports fully 16C450 compatible
- Bidirectional line printer port
- Software control of PS/2®-compatible enhancements (LPT Port, Mouse)
- CMOS direct drive of Centronics-type parallel interface
- PC/AT- or PS/2-compatible keyboard and mouse controller
- 146818A-compatible Real Time Clock (RTC)
- 16 bytes of additional standby RAM (66 bytes total)
- IDE bus control signals included (two external 74LS245 and one 74ALS244 - or equivalent - buffers are required)
- Seven battery-backed programmable chip select registers for auto configuration
- Preprogrammed default chip selects

- Programmable wait state generation
- 5 µA standby current for RTC, RAM, and chip select registers
- Single 128-pin plastic quad flatpack

### DESCRIPTION

The VL82C106 Combo chip replaces with a single 128-pin chip, several of the commonly used peripherals found in PC/AT-compatible computers. This chip when used with the VLSI PC/AT-compatible chip set allows designers to implement a very cost effective, minimum chip count motherboard containing functions that are common to virtually all PCs.

The on-chip UARTs are completely software compatible with the VL16C450 ACE.

The bidirectional parallel port provides a PS/2 software compatible interface between a Centronics-type printer and the VL82C106. Direct drive is provided so that all that is necessary to interface to the line printer port is a resistor - capacitor network. The bidirectional feature (option) is software programmable for backwards PC/AT-compatibility.

The keyboard/mouse controller is selectable as PC/AT- or PS/2-compatible.

The Real Time Clock is 146818A-compatible and offers a standby current drain of 5 µA at 3.0 V.

Included is the control logic necessary for the support of the Integrated Drive Electronics (IDE) hard disk bus interface.

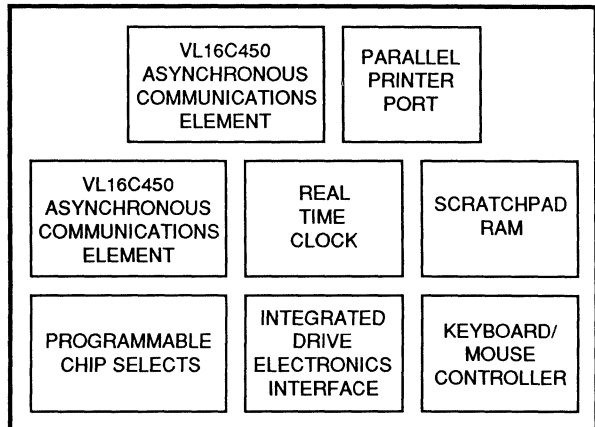
The Combo I/O chip also includes seven programmable chip selects, three internal and four external. Each chip select has a programmable 16-bit base address and a mask register that allows the number of bytes corresponding to each chip select to be programmed (e.g. 3F8H-3FFH has a base address of 3F8H and a range of 8 bytes). Each chip select can be programmed for number of wait states (0-7) and 8- or 16-bit operation. 16-bit decoding is used for all I/O addresses. A default fixed decode is provided on reset for the on-chip serial ports, printer port, and off-chip floppy and hard disk controllers, which may be changed to battery-backed programmable chip selects via a control bit.

### ORDER INFORMATION

Part Number	Package
VL82C106-FC	Plastic Quad Flatpack

**Note:** Operating temperature range is 0°C to +70°C.

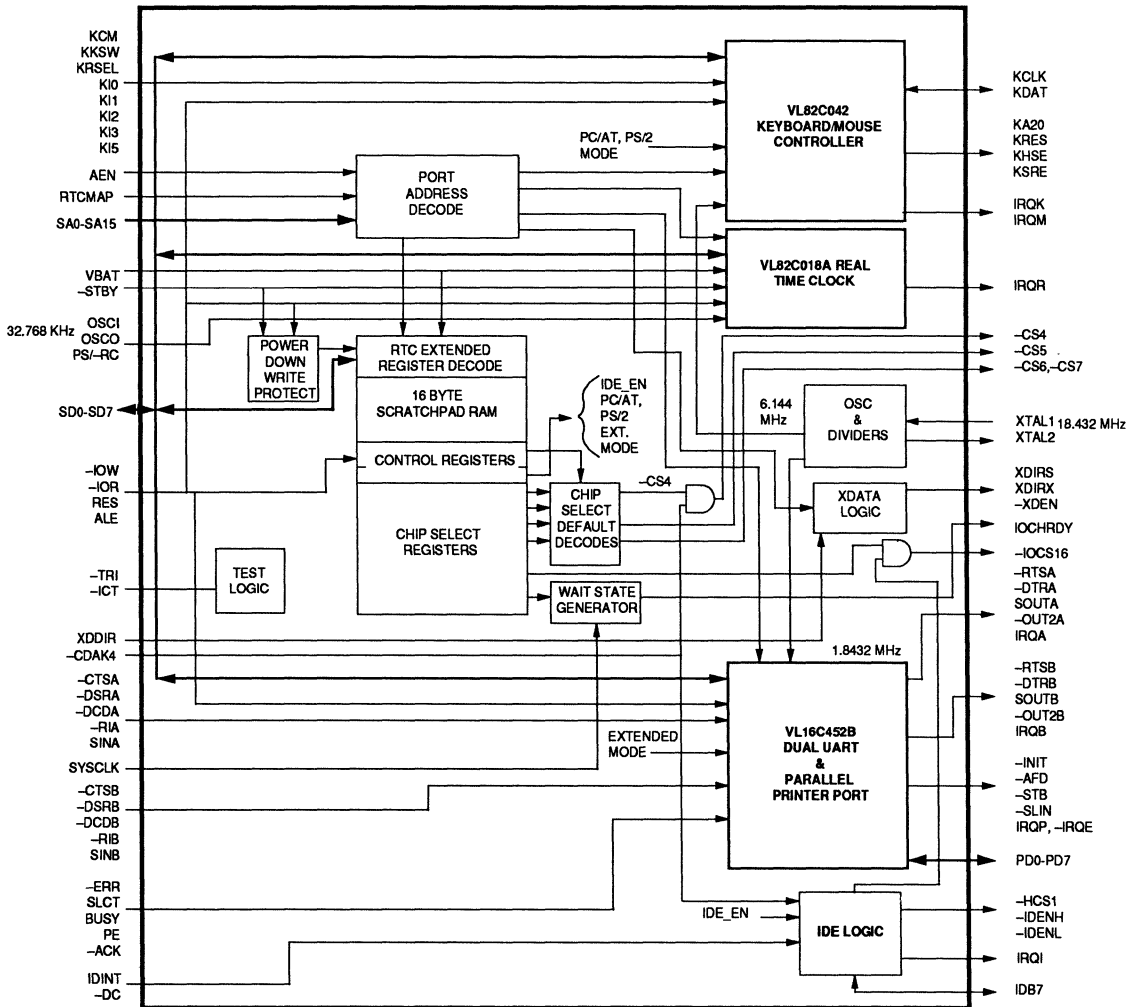
### INTERNAL FUNCTIONAL DIAGRAM



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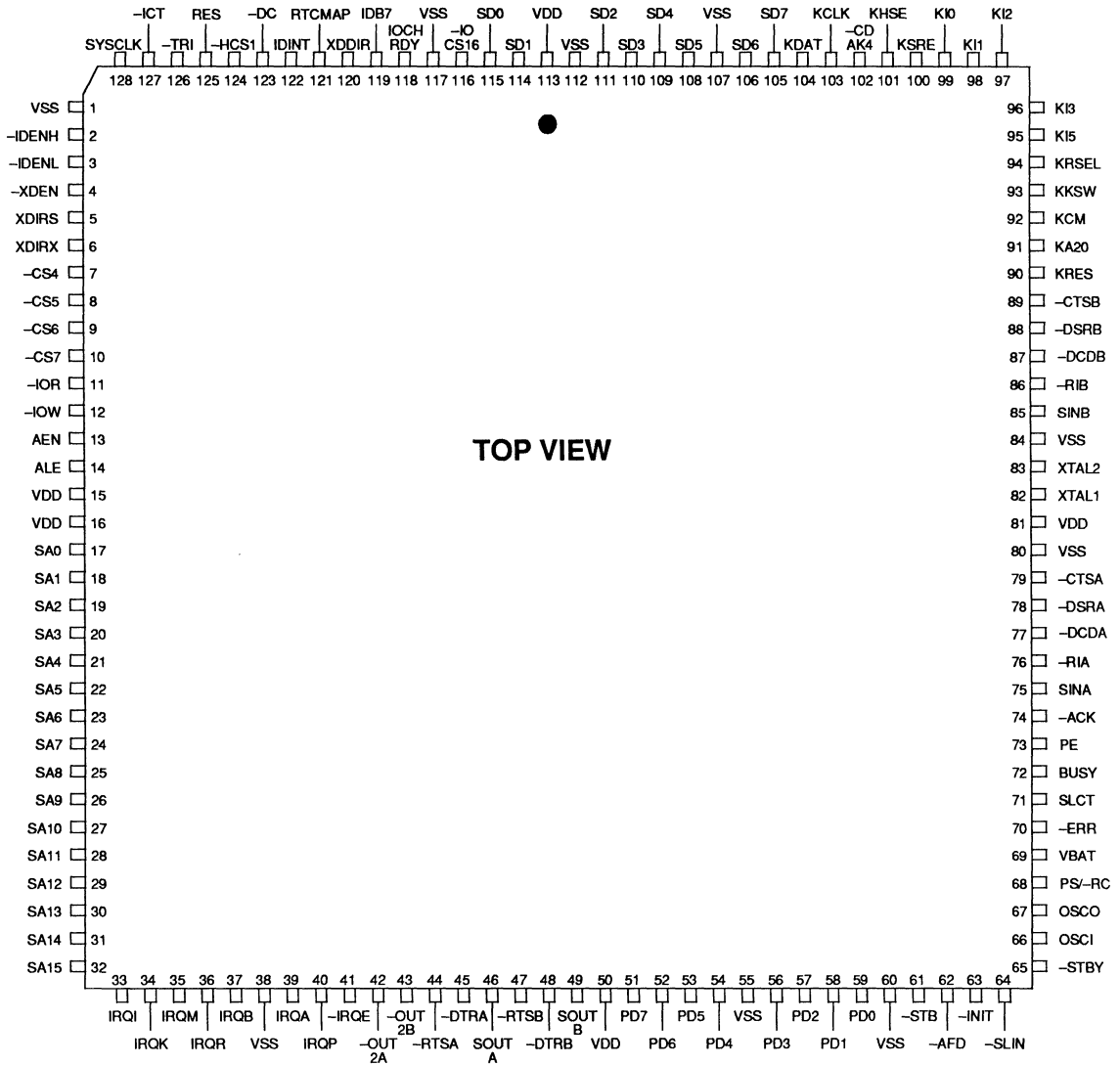
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BLOCK DIAGRAM



PIN DIAGRAM

VL82C106



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**SIGNAL DESCRIPTIONS**

<b>Signal Name</b>	<b>Pin Number</b>	<b>Signal Type</b>	<b>Signal Description</b>
<b>COMMUNICATIONS PORT A</b>			
-RTSA	44	O1	Request to Send, Port A
-DTRA	45	O1	Data Terminal Ready, Port A
SOUTA	46	O1	Serial Data Output, Port A
-CTSA	79	I4	Clear to Send, Port A
-DSRA	78	I4	Data Set Ready, Port A
-DCDA	77	I4	Data Carrier Detect, Port A
-RIA	76	I4	Ring Indicator, Port A
SINA	75	I4	Serial Input, Port A
IRQA	39	O6	Interrupt Request, Port A
-OUT2A	42	O1	Output 2, Port A
<b>COMMUNICATIONS PORT B</b>			
-RTSB	47	O1	Request to Send, Port B
-DTRB	48	O1	Data Terminal Ready, Port B
SOUTB	49	O1	Serial Data Output, Port B
-CTSB	89	I4	Clear to Send, Port B
-DSRB	88	I4	Data Set Ready, Port B
-DCDB	87	I4	Data Carrier Detect, Port B
-RIB	86	I4	Ring Indicator, Port B
SINB	85	I4	Serial Input, Port B
IRQB	37	O6	Interrupt Request, Port B
-OUT2B	43	O1	Output 2, Port B
<b>PARALLEL PRINTER PORT</b>			
PD0	59	I05	Printer Data Port, Bit 0
PD1	58	I05	Printer Data Port, Bit 1
PD2	57	I05	Printer Data Port, Bit 2
PD3	56	I05	Printer Data Port, Bit 3
PD4	54	I05	Printer Data Port, Bit 4
PD5	53	I05	Printer Data Port, Bit 5
PD6	52	I05	Printer Data Port, Bit 6
PD7	51	I05	Printer Data Port, Bit 7
-INIT	63	O4	Initialize Printer Signal
-AFD	62	O4	Autofeed Printer Signal
-STB	61	O4	Data Strobe to Printer
-SLIN	64	O4	Select Signal to Printer
-ERR	70	I4	Error Signal from Printer
SLCT	71	I4	Select Signal from Printer



**SIGNAL DESCRIPTIONS**

Signal Name	Pin Number	Signal Type	Signal Description
BUSY	72	I4	Busy Signal from Printer
PE	73	I4	Paper Error Signal from Printer
-ACK	74	I4	Acknowledge Signal from Printer
IRQP	40	O6	Printer Interrupt Request Output
-IRQE	41	O1	Printer Interrupt Request Enabled Signal
<b>REAL TIME CLOCK PORT</b>			
VBAT	69	NA	Standby Power - Normally 3 V to 5 V, battery backed.
-STBY	65	I5	Power Down Control
OSCI	66	NA	Crystal Connection Input - 32 KHz
OSCO	67	NA	Crystal Connection Output - 32 KHz
PS/-RC	68	I5	Power Sense/RAM Clear Input
IRQR	36	O1	Real Time Clock Interrupt Request Output
RTCMPA	121	I4	High - RTC is mapped to 70H and 71H, Low - RTC is mapped to 170H and 171H.
<b>KEYBOARD CONTROLLER PORT</b>			
KCLK	103	IO4	Keyboard Clock
KDAT	104	IO4	Keyboard Data
KCM	92	I4	General purpose input, normally color/monochrome.
KKSW	93	I4	General purpose input, normally keyboard switch.
KA20	91	O1	General purpose output, normally A20 Gate.
KRES	90	O1	General purpose output, normally reset.
KHSE	101	O1/IO4	General purpose input, normally speed select.
KSRE	100	O1/IO4	General purpose output, normally shadow RAM enable.
IRQK	34	O1	Keyboard Interrupt Request
IRQM	35	O1	Mouse Interrupt Request
KRSEL	94	I4	General purpose input, normally RAM select.
KI0	99	I4	General purpose input, bit 0.
KI1	98	I4	General purpose input, bit 1.
KI2	97	I4	General purpose input, bit 2.
KI3	96	I4	General purpose input, bit 3.
KI5	95	I4	General purpose input, bit 5.
<b>IDE BUS I/O</b>			
-IDENH	2	O1	IDE Bus Transceiver High Byte Enable
-IDENL	3	O1	IDE Bus Transceiver Low Byte Enable
IDINT	122	I4	IDE Bus Interrupt Request Input
IDB7	119	IO6	IDE Bus Data Bit 7
-DC	123	I4	Floppy Disk Change Signal
-HCS1	124	O1	IDE Host Chip Select 1
-IRQI	33	O6	IDE Interrupt Request Output

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**SIGNAL DESCRIPTIONS**


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<b>Signal Name</b>	<b>Pin Number</b>	<b>Signal Type</b>	<b>Signal Description</b>
<b>COMMON BUS I/O</b>			
SD0	115	IO2	System Bus Data, Bit 0
SD1	114	IO2	System Bus Data, Bit 1
SD2	111	IO2	System Bus Data, Bit 2
SD3	110	IO2	System Bus Data, Bit 3
SD4	109	IO2	System Bus Data, Bit 4
SD5	108	IO2	System Bus Data, Bit 5
SD6	106	IO2	System Bus Data, Bit 6
SD7	105	IO2	System Bus Data, Bit 7
SA0	17	I1	SystemBus Address, Bit 0
SA1	18	I1	System Bus Address, Bit 1
SA2	19	I1	System Bus Address, Bit 2
SA3	20	I1	System Bus Address, Bit 3
SA4	21	I1	System Bus Address, Bit 4
SA5	22	I1	System Bus Address, Bit 5
SA6	23	I1	System Bus Address, Bit 6
SA7	24	I1	System Bus Address, Bit 7
SA8	25	I1	System Bus Address, Bit 8
SA9	26	I1	System Bus Address, Bit 9
SA10	27	I1	System Bus Address, Bit 10
SA11	28	I1	System Bus Address, Bit 11
SA12	29	I1	System Bus Address, Bit 12
SA13	30	I1	System Bus Address, Bit 13
SA14	31	I1	System Bus Address, Bit 14
SA15	32	I1	System Bus Address, Bit 15
XTAL1	82	NA	Crystal/Clock Input - 18.432 MHz
XTAL2	83	NA	Crystal/Clock Output - 18.432 MHz
-IOR	11	I1	System Bus I/O Read
-IOW	12	I1	System Bus I/O Write
RES	125	I1	System Reset
AEN	13	I1	System Bus Address Enable
ALE	14	I1	System Bus Address Latch Enable
-IOCS16	116	O8	System Bus I/O Chip Select 16
IOCHRDY	118	O8	System Bus I/O Channel Ready
SYSCLK	128	I1	System Clock - Processor clock divide by 2.
-CS4	7	O1	Chip Select 4 - Normally for external floppy disk controller.
-CS5	8	O1	Chip Select 5 - Normally -HCS0 for IDE.

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**SIGNAL DESCRIPTIONS**

Signal Name	Pin Number	Signal Type	Signal Description
-CS6	9	O1	Chip Select 6 - Normally for external floppy disk controller.
-CS7	10	O1	Chip Select 7 - Normally for external floppy disk controller.
-CDAK4	102	I1	DMA Acknowledge forces -CS4 active.
XDDIR	120	I1	X Data Bus Transceiver Direction
XDIRS	5	O1	Modified X Data Bus Transceiver Direction Control Signal - Excludes real time clock and keyboard controller decodes.
XDIRX	6	O1	X Data Bus Transceiver Control Signal - Includes all CS decodes generated on chip.
-XDEN	4	O1	X Data Bus Transceiver Enable
-TRI	126	I4	Three-state Control Input - For all outputs to isolate chip for board tests.
-ICT	127	I4	In Circuit Test Mode Control
<b>POWER, GROUND, &amp; UNCOMMITTED</b>			
VDD	15, 16, 50, 81, 113		System Power: +5 V
VSS	1, 38, 55, 60, 80, 84, 107, 112, 117		System Ground

**I/O LEGEND**

	mA	Type	Comment
01	2	TTL	
02	24	TTL	
04	12	TTL-OD	Open drain, weak pull-up, no VDD diode
06	4	TTL-TS	Three-State
07	24	TTL-TS	Three-State
08	24	TTL-OD	Open drain, fast active pull-up
I1	-	TTL	
I2	-	CMOS	
I4	-	TTL	30k $\Omega$ pull-up
I5	-	TTL	Schmitt-trigger
I02	24	TTL-TS	Three-State
I04	12	TTL-OD	Open drain, slow turn-on
I05	12	TTL-TS	Three-State
I06	24	TTL-TS	Three-State, 30k $\Omega$ pull-up



**FUNCTIONAL DESCRIPTION**

Below is a detailed explanation of each of the major building blocks of the VL82C106 Combo chip. The following functional blocks are covered:

- 16C450 Serial Ports
- Parallel Printer Port
- 146818A-Compatible Real Time Clock
- Keyboard Controller
- Control and Chip Selects
- IDE Interface

**SERIAL COMMUNICATIONS PORTS**

The chip contains two UARTs, based on the VL16C450 Megacell core. Each of these UARTs share a common baud-rate clock, which is the XTAL1 input (18.432 MHz) divided by ten. The 18.432 MHz signal is shared with the keyboard controller, which divides it by three to get an approximate 6 MHz reference clock. Please refer to the VL16C452B data sheet for the register descriptions and timing parameters for the UARTs.

COMA is accessed via internally generated CS1, while COMB uses internally generated CS2.

**LINE PRINTER PORT**

The Line Printer Port contains the functionality of the port included in the VL16C452B, but offers a software programmable Extended Mode, which include a Direction Control Bit and Interrupt Status Bit. These features are disabled on initial power-up, but may be turned on by clearing the –EMODE bit of Control Register 0 (RTC Register 69H in AT or PS/2 mode or I/O PORT 102H in PS/2 mode). When the –EMODE bit is set, the part functions exactly as a PC/AT-compatible printer port.

The Line Printer Port is accessed via internally generated programmable chip select CS3.

**Register 0 - Line Printer Port Data**

The Line Printer (LPT) Port is either uni- or bidirectional, depending on the state of the Extended Mode and Data Direction Control bits.

Compatibility Mode (–EMODE bit = 1) - Read operations to this register return the last data that was written to the LPT

Port. Write operations immediately output data to the LPT Port.

Extended Mode (–EMODE bit = 0) - Read operations return either the data last written to the LPT Data Register if the Direction Bit is set to output ("0") or the data that is present on the pins of the LPT Port if the direction is set to input ("1"). Write operations latch data into the output register, but only drive the LPT Port when the Direction Bit is set to output.

In either case, the bits of the LPT Data Register are defined as follows:

Bit	Description
0	Data Bit 0
1	Data Bit 1
2	Data Bit 2
3	Data Bit 3
4	Data Bit 4
5	Data Bit 5
6	Data Bit 6
7	Data Bit 7

**Register 1 - LPT Port Status**

The LPT Status Register is a read-only register that contains interrupt status and real time status of the LPT connector pins. The bits are described as follows:

Bit	Description
0	Reserved
1	Reserved
2	–IRQ
3	–ERROR
4	SLCT
5	PE
6	–ACK
7	–BUSY

Bits 0 and 1 - Reserved, read as "1's".

Bit 2 - Interrupt Status bit, a "0" indicates that the printer has acknowledged the previous transfer with a ACK handshake (bit 4 of the control register must be set to "1").

When in AT mode, bit 1 RTC Register 6AH = 1, the IRQP output follows the –ACK input if enabled. When in PS/2 mode, IRQP is set during the inactive transition of the –ACK signal, and cleared following a read of the LPT status register.

Bit 3 - Error Status bit, a "0" indicates that the printer has had an error. A "1" indicates normal operation. This bit follows the state of the –ERR pin.

Bit 4 - Select Status bit, indicates the current status of the SLCT signal from the printer. A "0" indicates the printer is currently not selected (off-line). A "1" means the printer is currently selected.

Bit 5 - Paper Empty Status bit, a "0" indicates normal operation. A "1" indicates that the printer is currently out of paper. This bit follows the state of the PE pin.

Bit 6 - Acknowledge Status bit, a "0" indicates that the printer has received a character and is ready to accept another. A "1" indicates that the last operation to the printer has not been completed yet. This bit follows the state of the –ACK pin.

Bit 7 - Busy Status bit, a "0" indicates that the printer is busy and cannot receive data. A "1" indicates that the printer is ready to accept data. This bit is the inversion of the BUSY pin.

**Register 2 - LPT Port Control**

This port is a read/write port that is used to control the LPT direction as well as the Printer Control lines driven from the port. Write operations set or reset these bits, while read operations return the status of the last write operation to this register (except for bit 5 which is write only and is always read back as a "1"). The bits in this register are defined as follows:

Bit 0 - Printer Strobe Control bit, when set ("1") the STROBE signal is asserted on the LPT interface, causing the





Bit	Description
0	STROBE
1	AUTO FD XT
2	-INIT
3	SLCT IN
4	IRQ EN
5	DIR (Write Only)
6	Reserved
7	Reserved

printer to latch the current data. When reset ("0") the signal is negated.

Bit 1 - Auto Feed Control bit, when set ("1") the AUTO FD XT signal will be asserted on the LPT interface, causing the printer to automatically generate a line feed at the end of each line. When reset ("0") the signal is negated.

Bit 2 - Initialize Printer Control bit, when set ("1") the signal is negated. When reset ("0") the INIT signal is asserted to the printer, forcing a reset.

Bit 3 - Select Input Control bit, when set ("1") the SLCT IN signal is asserted, causing the printer to go "on-line". When reset ("0") the signal is negated.

Bit 4 - Interrupt Request Enable Control bit, when set ("1") enables interrupts from the LPT Port whenever the -ACK signal is asserted by the printer. When reset ("0") interrupts are disabled.

Bit 5 - When EMODE = 1, Direction (DIR) Control bit, when set ("1") the output buffers in the LPT Port are disabled, allowing data driven from external sources to be read from the LPT Port. When reset ("0"), the output buffers are enabled, forcing the LPT pins to drive the LPT pins. The power-on-reset value of this is cleared ("0"). When -EMODE = 1, this write only bit has no effect and should be read as "1".

Bits 6 and 7 - Reserved, read as "1's".

**REAL TIME CLOCK**

The Real Time Clock (RTC) is the equivalent of the Motorola MC146818A Real Time Clock component. It is also compatible with the Dallas Semiconductor DS1287A RTC when an external

battery and crystal are provided. Clock functions include the following:

- Time of Day Clock
- Alarm Function
- 100 Year Calendar Function
- Programmable Periodic Interrupt Output
- Programmable Square Wave Output
- 50 Bytes of User RAM
- User RAM Preset Feature

**RTC PROGRAMMERS MODEL**

The RTC memory consists of ten RAM bytes which contain the time, calendar, and alarm data, four control and status bytes, and 50 general purpose RAM bytes. The address map of the real time clock is shown below.

Add.	Function	Range
00-09	Time Regs.	0-99
0A	RTC Register A	(R/W)
0B	RTC Register B	(R/W)
0C	RTC Register C	(R O)
0D	RTC Register D	(R O)
0E-3F	User RAM (Standby)	

All 64 bytes are directly readable and writable by the processor program except for the following:

- 1) Registers C and D are read only.
- 2) Bit 7 of Register A is read only.

The RTC is normally accessed via internally decoded PORT 070H (RTC register address) and PORT 071H (RTC data read/write).

The RTC address and data ports can be moved to Port 170H, Port 171H by pulling the RTCMAP pin (121) to ground. This pin can be left not connected or tied high for normal port addressing.

The RTC address map also includes additional standby RAM, plus control registers for Combo chip configuration and chip select control. The RAM and Chip Select control registers are powered via the VBAT power supply for

battery-backed operation.

Add. (HEX)	Function
00-0D	Time Portion of RTC
0E-3F	RAM Portion of RTC
40-4F	Additional Standby RAM
50-68	Reserved
69-7F	Chip Select/Control Registers

The total address map is shown below: The processor program obtains time and calendar information by reading the appropriate locations. The program may initialize the time, calendar, and alarm by writing to these RAM locations. The contents of the ten time, calendar, and alarm bytes may be either binary or binary-coded decimal (BCD).

**Time of Day Register**

The contents of the Time of Day registers can be either in Binary or BCD format. They are relatively straightforward, but are detailed here for

Add.	Function	Range
0	Seconds (Time)	0-59
1	Seconds (Alarm)	0-59
2	Minutes (Time)	0-59
3	Minutes (Alarm)	0-59
4	Hours (Time)	1-12, 12 Hr Mode
4	Hours (Time)	0-23, 24 Hr Mode
5	Hours (Alarm)	0-23
6	Day of Week	1-7
7	Date of Month	1-31
8	Month	1-12
9	Year	0-99

completeness. The address map of these registers is shown next:

**Address 0 - Seconds (Time):** The range of this register is 0-59 in BCD mode, and 0-3BH in Binary mode.

**Address 1 - Seconds (Alarm):** The range of this register is 0-59 in BCD mode, and 0-3BH in Binary mode.

**Address 2 - Minutes (Time):** The range of this register is 0-59 in BCD mode, and 0-3BH in Binary mode.

**Address 3 - Minutes (Alarm):** The range of this register is 0-59 in BCD mode, and 0-3BH in Binary mode.

Range	Mode	Time
1-12	BCD	AM
81-92	BCD	PM
01H-0CH	Binary	AM
81H-8CH	Binary	PM

**Address 4 - Hours (Time):** The range of this register is:

Range	Mode	Time
1-12	BCD	AM
81-92	BCD	PM
01H-0CH	Binary	AM
81H-8CH	Binary	PM

**Address 5 - Hours (Alarm):** The range of this register is:

**Address 6 - Day of Week:** The range of this register is 1-7 in BCD mode, and 1-7H in Binary mode.

**Address 7 - Date:** The range of this register is 1-31 in BCD mode, and 1-1FH in Binary mode.

**Address 8 - Month:** The range of this register is 1-12 in BCD mode, and 1-0CH in Binary mode.

**Address 9 - Year:** The range of this register is 0-99 in BCD mode, and 0-63H in Binary mode.

### RTC CONTROL REGISTER

The RTC has four registers which are accessible to the processor program. The four registers are also fully accessible during the update cycle.

Add.	Function	Type
0A	RTC Register A	R/W
0B	RTC Register B	R/W
0C	RTC Register C	R O
0D	RTC Register D	R O
0E-3F	User RAM (Standby)	R/W

### Register A

This register contains control bits for the selection of Periodic Interrupt, Input Divisor, and the Update In Progress Status bit. The bits in the register are defined as follows:

Bit	Description	Abbr.
0	Rate Select Bit 0	RS0
1	Rate Select Bit 1	RS1
2	Rate Select Bit 2	RS2
3	Rate Select Bit 3	RS3
4	Divisor Bit 0	DV0
5	Divisor Bit 1	DV1
6	Divisor Bit 2	DV2
7	Update In Progress	UIP

**Bits 0 to 3 -** The four rate selection bits (RS0 to RS3) select one of 15 taps on the 22-stage divider, or disable the divider output. The tap selected may be used to generate a periodic interrupt. These four bits are read/write bits which are not affected by RESET. The Periodic Interrupt Rate that results from the selection of various tap values is as follows:

RS Value	Periodic Interrupt Rate
0	None
1	3.90625 ms
2	7.8125 ms
3	122.070 $\mu$ s
4	244.141 $\mu$ s
5	488.281 $\mu$ s
6	976.562 $\mu$ s
7	1.953125 ms
8	3.90625 ms
9	7.8125 ms
0AH	15.625 ms
0BH	31.25 ms
0CH	62.5 ms
0DH	125 ms
0EH	250 ms
0FH	500 ms

**Bits 4 to 6 -** The three Divisor Selection bits (DV0 to DV2) are fixed to provide for only a five-state divider chain, which would be used with a 32 KHz external crystal. Only bit 6 of this register can be changed allowing control of the reset for the divisor chain. When the divider reset is removed, the first update cycle begins one-half second later. These bits are not affected by power-on reset (external pin).

DV Value	Condition
2	Operation Mode, Divider Running
6	Reset Mode, Divider in Reset State

**Bit 7 -** The Update In Progress (UIP) bit is a status flag that may be monitored by the program. When UIP is a "1", the update cycle is in progress or will soon begin. When UIP is a "0", the update cycle is not in progress and will not be for at least 244  $\mu$ s. The time, calendar, and alarm information in RAM is fully available to the program when the UIP

bit is "0". The UIP bit is a read-only bit, and is not affected by reset. Writing the SET bit in Register B to a "1" will inhibit any update cycle and then clear the UIP status bit.

### Register B

Register B contains command bits to control various modes of operations and interrupt enables for the RTC. The bits in this register are defined as follows:

Bit	Description	Abbr.
0	Daylight Savings Enable	DSE
1	24/12 Mode	24/12
2	Data Mode (Binary or BCD)	DM
3	Not Used	
4	Update End Interrupt Enable	UIE
5	Alarm Interrupt Enable	AIE
6	Periodic Interrupt Enable	PIE
7	Set Command	SET

**Bit 0 - The Daylight Savings Enable (DSE) bit** is a read/write bit which allows the program to enable two special updates (when DSE is "1"). On the first Sunday in April the time increments from 1:59:59 AM to 3:00:00 AM. On the first Sunday in October when the time first reaches 1:59:59 AM it changes to 1:00:00 AM. These special updates do not occur when the DSE bit is a "0". DSE is not changed by any internal operations or reset.

**Bit 1 - The 24/12 control bit** establishes the format of the hours bytes as either the 24-hour mode ("1") or the 12-hour mode ("0"). This is a read/write bit, which is affected only by software.

**Bit 2 - The Data Mode (DM) bit** indicates whether time and calendar updates are to use binary or BCD formats. The DM bit is written by the processor program and may be read by the program, but is not modified by any internal functions or reset. A "1" in DM signifies binary data, while a "0" in DM specifies binary-coded-decimal (BCD) data.

**Bit 3 - This bit** is unused in this version of the RTC, but is used for Square Wave Enable in the Motorola MC146818.

**Bit 4 - The UIE (Update End Interrupt Enable) bit** is a read/write bit which enables the Update End Interrupt Flag (UF) bit in Register C to assert an IRQ. The reset pin being asserted or the SET bit going high clears the UIE bit.

**Bit 5 - The Alarm Interrupt Enable (AIE) bit** is a read/write bit which when set to a "1" permits the Alarm Interrupt Flag (AF) bit in Register C to assert an IRQ. An alarm interrupt occurs for each second that the three time bytes equal the three alarm bytes (including a "don't care" alarm code of 11XXXXXb). When the AIE bit is a "0", the AF bit does not initiate an IRQ signal. The reset pin clears AIE to "0". The internal functions do not affect the AIE bit.

**Bit 6 - The Periodic Interrupt Enable (PIE) bit** is a read/write bit which allows the Periodic Interrupt Flag (PF) bit in Register C to cause the IRQ pin to be driven low. A program writes a "1" to the PIE bit in order to receive periodic interrupts at the rate specified by the RS3, RS2, RS1, and RS0 bits in Register A. A "0" in PIE blocks IRQ from being initiated by a periodic interrupt, but the Periodic Interrupt Flag (PF) bit is still set at the periodic rate. PIE is not modified by any internal functions, but is cleared to "0" by a reset.

**Bit 7 - When the SET bit** is a "0", the update cycle functions normally by advancing the counts once-per-second. When the SET bit is written to a "1", any update cycle in progress is aborted and the program may initialize the time and calendar bytes without an update occurring in the midst of initializing. SET is a read/write bit which is not modified by reset or internal functions.

### Register C

Register C contains status information about interrupts and internal operation of the RTC. The bits in this register are defined as follows:

Bit	Description	Abbr.
0	Not Used, Read as 0	
1	Not Used, Read as 0	
2	Not Used, Read as 0	
3	Not Used, Read as 0	
4	Update End Interrupt Flag	UF
5	Alarm Interrupt Flag	AF
6	Periodic Interrupt Flag	PF
7	IRQ Pending Flag	IRQF

Bits 0 to 3 - The unused bits of Status Register 1 are read as "0's", and cannot be written.

**Bit 4 - The Update Ended Interrupt Flag (UF) bit** is set after each update cycle. When the UIE bit is a "1", the "1" in UF causes the IRQF bit to be a "1", asserting IRQ. UF is cleared by a Register C read or a reset.

**Bit 5 - A "1" in the AF (Alarm Interrupt Flag) bit** indicates that the current time has matched the alarm time. A "1" in the AF causes the IRQ pin to go low, and a "1" to appear in the IRQF bit, when the AIE bit also is a "1". A reset or a read of Register C clears AF.

**Bit 6 - The Periodic Interrupt Flag (PF) bit** is a read only bit which is set to a "1" when a particular edge is detected on the selected tap of the divider chain. The RS3 to RS0 bits establish the periodic rate. PF is set to a "1" independent of the state of the PIE bit. PF being a "1" initiates an IRQ signal and sets the IRQF bit when PIE is also a "1". The PF bit is cleared by a reset or a software read of Register C.

**Bit 7 - The Interrupt Request Pending Flag (IRQF) bit** is set to a "1" when one or more of the following are true:

$$\begin{aligned} \text{PF} &= \text{PIE} = 1 \\ \text{AF} &= \text{AIE} = 1 \\ \text{UF} &= \text{UIE} = 1 \end{aligned}$$

The logic can be expressed in equation form as:

$$\text{IRQF} = \text{PF} \cdot \text{PIE} + \text{AF} \cdot \text{AIE} + \text{UF} \cdot \text{UIE}$$



Any time the IRQF bit is a "1", the IRQ pin is asserted. All flag bits are cleared after Register C is read by the program or when the reset pin is asserted.

**Register D**

This register contains a bit that indicates the status of the on-chip standby RAM. The contents of the registers are described as the following:

Bit	Description	Abbr.
0	Not Used, Read as 0	
1	Not Used, Read as 0	
2	Not Used, Read as 0	
3	Not Used, Read as 0	
4	Not Used, Read as 0	
5	Not Used, Read as 0	
6	Not Used, Read as 0	
7	Valid RAM Data and Time	VRT

Bits 0 to 6 - The remaining bits of Register D are unused. They cannot be written, but are always read as "0's".

Bit 7 - The Valid RAM Data and Time (VRT) bit indicates the condition of the contents of the RAM, provided the power sense (PS) pin is satisfactorily connected. A "0" appears in the VRT bit when the power-sense pin is low. The processor program can set the VRT bit when the time and calendar are initialized to indicate that the RAM and time are valid. The VRT is a read only bit which is not modified by the reset pin. The VRT bit can only be set by reading Register D.

Pulling the PS-RC pin low for a minimum of 2  $\mu$ s also sets all RAM bytes from address OE through 3F to all ones.

**CMOS STANDBY RAM**

The 66 general purpose RAM bytes are not dedicated within the RTC. They can be used by the processor program, and are fully available during the update cycle.

**GENERAL RTC NOTES**

**Set Operation**

Before initializing the internal registers, the SET bit in Register B should be set to a "1" to prevent time/calendar updates from occurring. The program initializes the ten locations in the selected format (binary or BCD), then indicates the format in the Data Mode (DM) bit of Register B. All ten time, calendar, and alarm bytes must use the same Data Mode, either binary or BCD. The SET bit may now be cleared to allow updates. Once initialized the RTC makes all updates in the selected Data Mode. The Data Mode cannot be changed without reinitializing the ten data bytes.

**BCD vs Binary Format**

The 24/12 bit in Register B establishes whether the hour locations represent 1-to-12 or 0-to-23. The 24/12 bit cannot be changed without reinitializing the hour locations. When the 12-hour format is selected, the high-order bit of the hours byte represents PM when it is a "1".

**Update Operation**

The time, calendar, and alarm bytes are not always accessible by the processor program. Once-per-second the ten bytes are switched to the update logic to be advanced by one second and to check for an alarm condition. If any of the ten bytes are read at this time, the data outputs are undefined. The update lockout time is 1948  $\mu$ s for the 32.768 KHz time base. The Update Cycle section shows how to accommodate the Update Cycle in the processor program.

**Alarm Operation**

The three alarm bytes may be used in two ways. First, when the program inserts an alarm time in the appropriate hours, minutes, and seconds alarm locations, the Alarm Interrupt is initiated at the specified time each day if the alarm enable bit is high. The second usage is to insert a "don't care" state in one or more of three alarm bytes. The "don't care" code is any byte from 0C0h to 0FFh. An Alarm Interrupt each hour is created with a "don't care" code in the hours alarm location. Similarly, an alarm is generated every minute with "don't care" codes in the hours and minutes alarm bytes. The "don't care"

codes in all three alarm bytes create an interrupt every second.

**Interrupts**

The RTC plus RAM includes three separate fully automatic sources of interrupts to the processor. The Alarm Interrupt may be programmed to occur at rates from one-per-second to one-a-day. The Periodic Interrupt may be selected for rates from half-a-second to 30.517  $\mu$ s. The Update Ended Interrupt may be used to indicate to the program that an update cycle is completed.

The processor program selects which interrupts, if any, it wishes to receive. Three bits in Register B enable the three interrupts. Writing a "1" to an interrupt-enable bit permits that interrupt to be initiated when the event occurs. A "0" in the interrupt-enable bit prohibits the IRQ pin from being asserted due to the interrupt cause.

If an interrupt flag is already set when the interrupt becomes enabled, the IRQ pin is immediately activated, though the interrupt initiating the event may have occurred much earlier. Thus, there are cases where the program should clear such earlier initiated interrupts before first enabling new interrupts.

When an interrupt event occurs, a flag bit is set to a "1" in Register C. Each of the three interrupt sources have separate flag bits in Register C, which are set independent of the state of the corresponding enable bits in Register B. The flag bit may be used with or without enabling the corresponding enable bits.

**Divider Control**

The Divider Control bits are fixed for only 32.768 KHz operation. The divider chain may be held in reset, which allows precision setting of the time. When the divider is changed from reset to an operating time base, the first update cycle is one-half a second later. The Divider Control bits are also used to facilitate testing the RTC.

**Periodic Interrupt Selection**

The Periodic Interrupt allows the IRQ pin to be triggered from once every 500 ms to once every 30.517  $\mu$ s. The Periodic Interrupt is separate from the Alarm Interrupt which may be output from once-per-second to once-per-day.

**KEYBOARD CONTROLLER**

The keyboard controller on-chip ROM contains the code that is required to support the PC/AT and PS/2 command sets and 128 bytes of conversion code.

Keyboard serial I/O is handled with hardware implementations of the receiver and transmitter. Both functions depend on an 8-bit timer for time-out detection. Enhanced status reporting is provided in hardware to simplify error handling in software. This logic is duplicated for the mouse interface.

User RAM support is provided. The program writes a command 20-3FH (read) or 60-7FH (write) with the lower five bits representing the RAM address. Data from a read or for a write are accessed through port 60H DBB.

Parallel Port 1 (input) is provided and Parallel Port 2 (output) has defined functions depending on whether the controller is in PC/AT or PS/2 mode.

Support for PORT 60H DBB (reads and writes) and Status Register (reads and writes) is provided in hardware for interface to the PC host.

**KEYBOARD CONTROLLER INTERFACE TO PC/AT**

The interface to the PC/AT consists of one register pair (PORT 60H/64H) for the keyboard and mouse.

The PORT 60H read operations output the contents of the Output Buffer to D0-D7 and clears the status of the Output Buffer Full (OBF/Status Register bit 0) bit.

Status read operations output the contents of the Status Register to D0-D7. No status is changed as a result of the read operation.

The PORT 60H write operations cause the Input Buffer DBB to be changed. The state of the C/D bit is cleared (Status Register bit 3, "0" indicates data) and the Input Buffer Full (IBF/Status Register bit 1) bit is set ("1").

Command write operations are to PORT 64H. The C/D bit will be set to ("1") when a valid command has been written to PORT 64H.

**KEYBOARD PORT INTERFACE PROTOCOL**

Data transmission between the controller, the keyboard, and mouse consist of a synchronous bit stream over the data and clock lines. The bits are defined as follows:

Bit	Function
1	Start Bit (Always 0)
2	Data Bit 0 (LSB)
3-8	Data Bits 1-6
9	Data Bit 7 (MSB)
10	Parity Bit (Odd)
11	Stop Bit (Always 1)

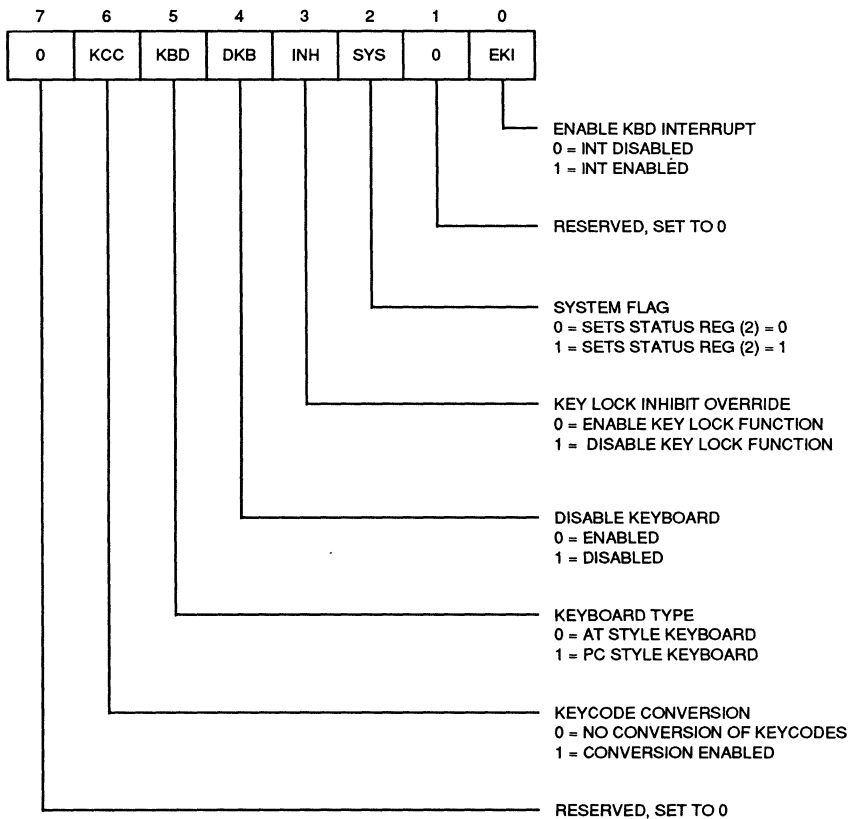
**PROGRAMMER INTERFACE**

The programmer interface to the keyboard controller is quite simple, consisting of four registers:

Register	R/W	I/O
Status	R	64H
Command	W	64H
Output Buffer	R	60H
Input Buffer	W	60H

The behavior of these registers differ according to the mode of operation (PC/AT or PS/2). There exists only one mode register and one Status Register with different bit definitions for PC/AT mode and PS/2 mode. The bit definitions for each register in each mode follows.

**FIGURE 1. PC/AT MODE REGISTER (READ PORT 60H AFTER WRITE COMMAND 20H TO PORT 64H)**



**PC/AT MODE REGISTER**

Bit 0 - Enable Keyboard Interrupt (EKI), when set ("1") causes the controller to generate a keyboard interrupt whenever data (keyboard or controller) is written into the output buffer.

Bit 1 - Reserved, should be written as "0".

Bit 2 - System Flag (SYS), when set ("1") writes the System Flag bit of the Status Register to "1". This bit is used

to indicate a switch from virtual to real mode when set.

Bit 3 - Inhibit Override (INH), when set ("1") disables the keyboard lock function (KCSW Input).

Bit 4 - Disable Keyboard (DKB), when set ("1") disables the keyboard by holding the -KCKOUT line low.

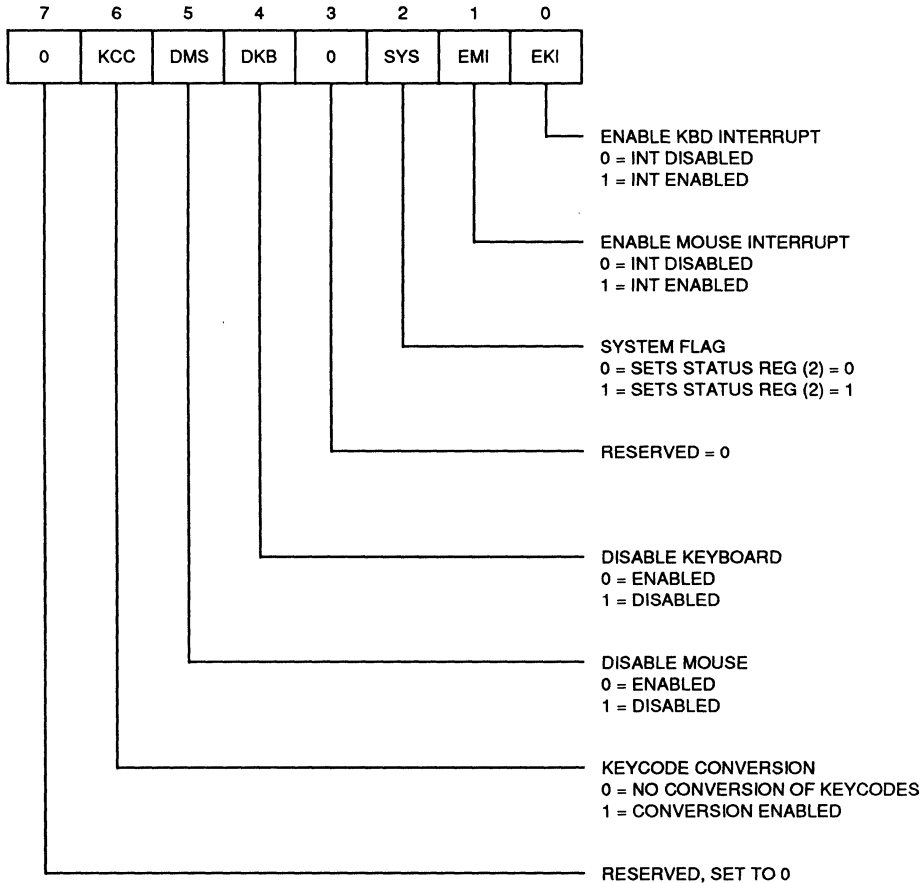
Bit 5 - Keyboard Type (KBD), when set ("1") allows for compatibility with PC-

style keyboards. In this mode, parity is not checked and scan codes are not converted.

Bit 6 - Keycode Conversion (KCC), when set ("1") causes the controller to convert the scan codes to PC format. When reset, the codes (AT keyboard) are passed along unconverted.

Bit 7 - Reserved, should be written as "0".

FIGURE 2. PS/2 MODE REGISTER (READ PORT 60H AFTER WRITE COMMAND 20H TO PORT 64H)



**PS/2 MODE REGISTER**

Bit 0 - Enable Keyboard Interrupt (EKI), when set ("1") causes the controller to generate a keyboard interrupt whenever data (keyboard or command) is written into the output buffer.

Bit 1 - Enable Mouse Interrupt (EMI), when set ("1") allows the controller to generate a mouse interrupt when mouse data is available in the output register.

Bit 2 - System Flag (SYS), when set ("1") writes the System Flag bit of the Status Register to "1". This bit is used to indicate a switch from virtual to real mode when set.

Bit 3 - Reserved, "0".

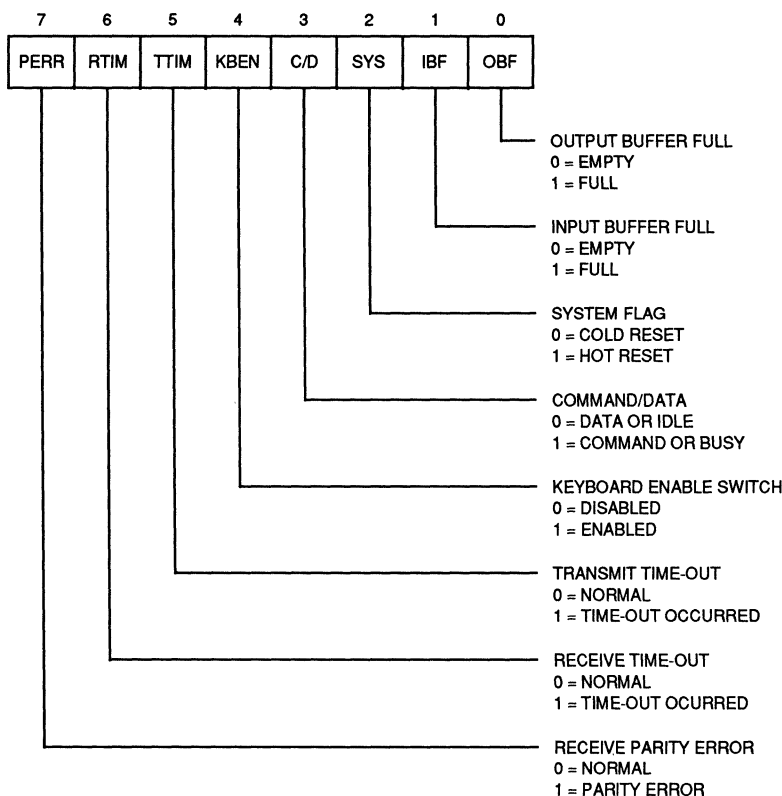
Bit 4 - Disable Keyboard (DKB), when set ("1") disables the keyboard by holding the -KCKOUT low.

Bit 5 - Disable Mouse (DMS), when set ("1") disables the mouse by holding the -MCKOUT low.

Bit 6 - Keycode Conversion (KCC), when set ("1") causes the controller to convert the scan codes to PC format. When reset, the codes (PS/2 keyboard) are passed along unconverted.

Bit 7 - Reserved, "0".

FIGURE 3. PC/AT STATUS REGISTER (READ ONLY - PORT 64H)



**PC/AT Status Register**

Bit 0 - Output Buffer Full (OBF), when set ("1") indicates that data is available in the controller Data Bus Buffer, and that the CPU has not read the data yet. CPU reads to PORT 60H to reset the state of this bit.

Bit 1 - Input Buffer Full (IBF), when set ("1") indicates that data has been written to PORT 60H or 64H, and the controller has not read the data.

Bit 2 - System Flag (SYS), when set ("1") indicates that the CPU has changed from virtual to real mode.

Bit 3 - Command/Data (CD), when set ("1") indicates that a command has been placed into the Input Data Buffer of the controller. The controller uses this bit to determine if the byte written is a command to be executed.

Bit 4 - Keyboard Enable (KBEN), indicates the state of the "keyboard inhibit" switch input (KKSWS). "0" indicates the keyboard is inhibited.

Bit 5 - Transmit Time-out (TTIM), when set ("1") indicates that a transmission to the keyboard was not completed before the controller's internal timer timed-out.

Bit 6 - Receive Time-out (RTIM), when set ("1") indicates that a transmission from the keyboard was not completed before the controller's internal timer timed-out.

Bit 7 - Parity Error (PERR), when set ("1") indicates that a parity error (even parity = error) occurred during the last transmission (received scan code) from the keyboard. When a parity error is detected, the output buffer is loaded with FFH, the OBF Status bit is set and the KIRQ pin is set ["1" if the EKI bit/ Mode Register bit 0 is set ("1")].



**FIGURE 4. PC/AT KEYBOARD SCAN CODE TRANSLATION TO PC/XT SCAN CODE**

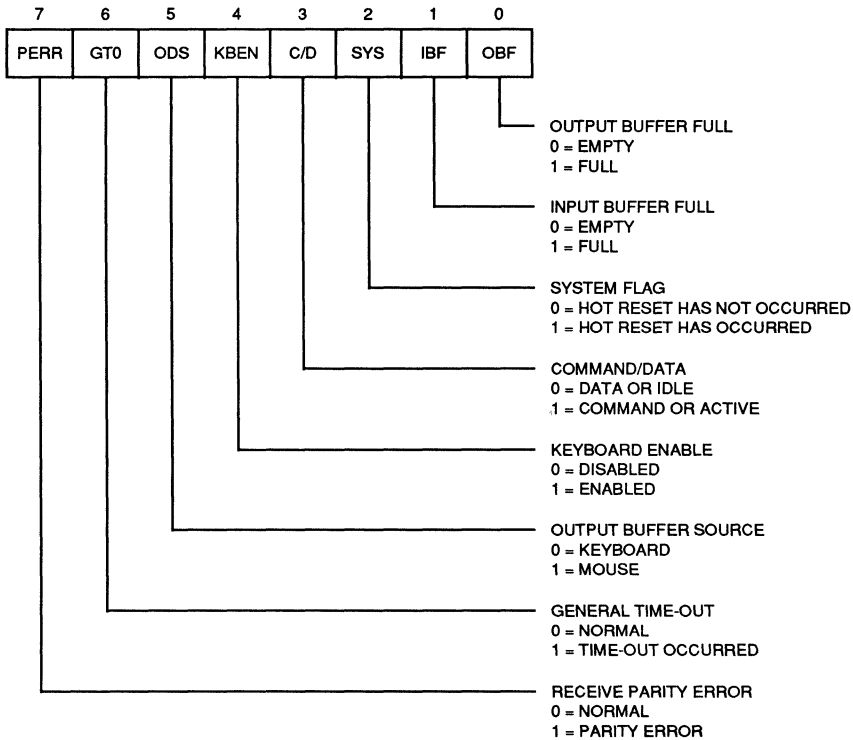
KEYBOARD SCAN CODE	SYSTEM SCAN CODE	KEYBOARD SCAN CODE	SYSTEM SCAN CODE	KEYBOARD SCAN CODE	SYSTEM SCAN CODE
00	ff	30	69	60	55
01	43	31	31	61	56
02	41	32	30	62	77
03	3f	33	23	63	78
04	3d	34	22	64	79
05	3b	35	15	65	7a
06	3c	36	07	66	0e
07	58	37	5e	67	7b
08	64	38	6a	68	7c
09	44	39	72	69	4f
0a	42	3a	32	6a	7d
0b	40	3b	24	6b	4b
0c	3e	3c	16	6c	47
0d	0f	3d	08	6d	7e
0e	29	3e	09	6e	7f
0f	59	3f	5f	6f	6f
10	65	40	6b	70	52
11	38	41	33	71	53
12	2a	42	25	72	50
13	70	43	17	73	4c
14	1d	44	18	74	4d
15	10	45	0b	75	48
16	02	46	0a	76	01
17	5a	47	60	77	45
18	66	48	6c	78	57
19	71	49	34	79	4e
1a	2c	4a	35	7a	51
1b	1f	4b	26	7b	4a
1c	1e	4c	27	7c	37
1d	11	4d	19	7d	49
1e	03	4e	0c	7e	46
1f	5b	4f	61	7f	54
20	67	50	6d		
21	2e	51	73		
22	2d	52	28		
23	20	53	74		
24	12	54	1a		
25	05	55	0d		
26	04	56	62		
27	5c	57	6e		
28	68	58	3a		
29	39	59	36		
2a	2f	5a	1c		
2b	21	5b	1b		
2c	14	5c	75		
2d	13	5d	2b		
2e	06	5e	63		
2f	5d	5f	76		

The following scan codes are converted by inline code:

KEYBOARD SCAN CODE	SYSTEM SCAN CODE
83	41
84	54

**Note:** All other PC/AT scan codes are passed to the system untranslated.

FIGURE 5. PS/2 STATUS REGISTER (READ ONLY - PORT 64H)



**PS/2 Status Register**

Bit 0 - Output Buffer Full (OBF), when set ("1") indicates that data is available in the controller Data Bus Buffer, and that the CPU has not read the data yet. The CPU reads to PORT 60H reset the state of this bit.

Bit 1 - Input Buffer Full (IBF), when set ("1") indicates that data has been written to PORT 60H or 64H, and the controller has not read the data.

Bit 2 - System Flag (SYS), when set ("1") indicates that the CPU has changed from virtual to real mode.

Bit 3 - Command/Data (CD), when set ("1") indicates that a command has been placed into the Input Data Buffer

of the controller. The controller uses this bit to determine if the byte written is a command to be executed. This bit is not reset until the command has completed its operation.

Bit 4 - Keyboard Enable (KBEN) indicates the state of the "keyboard inhibit" switch input (KKS<sub>W</sub>). "0" indicates the keyboard is inhibited.

Bit 5 - Output Buffer Data Source (ODS), when set ("1") indicates that the data in the output buffer is mouse data. When reset, it indicates the data is from the keyboard.

Bit 6 - Time-out Error (TERR), when set ("1") indicates that a transmission was

started and that it did not complete within the normal time taken (approximately 11 KCKIN cycles). If the transmission originated from the controller, a FEH is placed in the output buffer. If the transmission originated from the keyboard, a FFH is placed in the output buffer.

Bit 7 - Parity Error (PERR), when set ("1") indicates that a parity error (even parity = error) occurred during the last transmission from the keyboard. When a parity error is detected, the output buffer is loaded with FFH, the OBF Status bit is set and the KIRQ pin is set ["1" if the EK1 bit/Mode Register bit 0 is set ("1")].

**COMMAND SET**

The command set supported by the keyboard controller supports two modes of operation, and a set of extensions to the AT command set for the PS/2. In both modes, the command is implemented by writing the command byte to PORT 64H. Any subsequent data is read from PORT 60H (see description of command 20) or written to PORT 60H (see description of command PORT 60H). The commands for each mode are shown in the table below:

**PC/AT Mode:**

Comm.	Description
20	Read Mode Register
21-3F	Read Keyboard Controller RAM (Byte 1-31)
60	Write Mode Register
61-7F	Write Keyboard Controller RAM (Byte 1-31)
AA	Self Test
AB	KBD Interface Test
AC	Diagnostic Dump
AD	Disable Keyboard
AE	Enable Keyboard
C0	Read Input Port (P10-P17)
D0	Read Output Port (P20-P27)
D1	Write Output Port
E0	Read Test Inputs (T0, T1)
F0-FF	Pulse Output Port (P20-P27)

Note: If data is written to the data buffer (PORT 60H) and the command preceding it did not expect data from the port (PORT 60H) the data will be transmitted to the keyboard.

**Added PS/2 Commands:**

Comm.	Description
A4	Test Password
A5	Load Password
A6	Enable Password
A7	Disable Mouse
A8	Enable Mouse
A9	Mouse Interface Test
C1	Poll in Port Low (P10-P13 -> S4-S7)
C2	Poll in Port High (P14-P17 -> S4-S7)
D1	Write Output Port
D2	Write Keyboard Output Buffer
D3	Write Mouse Output Buffer
D4	Write to Mouse

The following is a description of each command:

- 20 Read the keyboard controller's Mode Register (PC/AT and PS/2) - The keyboard controller sends its current mode byte to the output buffer (accessed by a read of PORT 60H).
- 21-3F Read the keyboard controller's RAM (PC/AT and PS/2) - Bits D4-D0 specify the address.
- 60 Write the keyboard controller's Mode Register (PC/AT and PS/2) - The next byte of data written to the keyboard data port (PORT 60H) is placed in the controller's mode register.
- 61-7F Write the keyboard controller's RAM (PC/AT and PS/2) - This command writes to the internal keyboard controller RAM with the address specified in bits D4-D0.
- A4 Test Password Installed (PS/2 only) - This command checks if there is currently a password installed in the controller. The test result is placed in the output buffer (the OBF bit is set) and KIRQ is asserted (if the EKI bit is set). Test result - FAH means

that the password is installed, and F1H means that it is not.

- A5 Load Password (PS/2 only) - This command initiates the password load procedure. Following this command, the controller will take data from the input buffer port (PORT 60H) until a 00H is detected or a full eight byte password including a delimiter (e.g. <cr>) is loaded into the password latches. Note: this means that during password validation, the password can be a maximum of seven bytes with a delimiter such as <cr>.
- A6 Enable Password (PS/2 only) - This command enables the security feature. The command is valid only when a password pattern is written into the controller (see A5 command). No other commands will be "honored" until the security sequence is completed and command A6 is cleared.
- A7 Disable Mouse (PS/2 only) - This command sets bit 5 of the Mode Register which disables the mouse by driving the -MCKOUT line low.
- A8 Enable Mouse (PS/2 only) - This command resets bit 5 of the Mode Register, thus enabling the mouse.
- A9 Mouse Interface Test (PS/2 only) - This command causes the controller to test the mouse clock and data lines. The results are placed in the output buffer (the OBF bit is set) and the KIRQ line is asserted (if the EKI bit is set). The results are as follows:

Data	Meaning
00	No Error
01	Mouse Clock Line Stuck Low
02	Mouse Clock Line Stuck High
03	Mouse Data Line Stuck Low
04	Mouse Data Line Stuck High



**AA** Self Test command (PC/AT and PS/2) - This commands the controller to perform internal diagnostic tests. A 55H is placed in the output buffer if no errors were detected. The OBF bit is set and KIRQ is asserted (if the EKI bit is set).

**AB** Keyboard Interface Test (PC/AT and PS/2) - This command causes the controller to test the keyboard clock and data lines. The test result is placed in the output buffer (the OBF bit is set) and the KIRQ line is asserted (if the EKI bit is set). The results are as follows:

Data	Meaning
00	No Error
01	Keyboard Clock Line Stuck Low
02	Keyboard Clock Line Stuck High
03	Keyboard Data Line Stuck Low
04	Keyboard Data Line Stuck High

**AC** Diagnostic Dump (PC/AT only, Reserved on PS/2) - Sends 16 bytes of the controller's RAM, the current state of the input port, and current state of the output port to the system.

**AD** Keyboard Disable (PC/AT and PS/2) - This command sets bit 4 of the Mode Register to a "1". This disables the keyboard by driving the clock line (-KCKOUT) high. Data will not be sent or received.

**AE** Keyboard Enable (PC/AT and PS/2) - This command resets bit 4 of the mode byte to a "0". This enables the keyboard again by allowing the keyboard clock to free-run.

**C0** Read P1 Input Port (PC/AT and PS/2) - This command reads the keyboard input port and places it in the output buffer. This command overwrites the data in the buffer.

**C1** Poll Input Port low (PS/2 only) - P1 bits 0-3 are written into Status

Register bits 4-7 until a new command is issued to the keyboard controller.

**C2** Poll Input Port high (PS/2 only) - P1 bits 4-7 are written into Status Register bits 4-7 until a new command is issued to the keyboard controller.

**D0** Read Output Port (PC/AT and PS/2) - This command causes the controller to read the P2 output port and place the data in its output buffer. The definitions of the bits are as follows:

Bit	Pin	PC/AT Mode	PS/2 Mode
0	P20	-RC	-RC
1	P21	A20 Gate	A20 Gate
2	P22	Speed Sel	-MDOUT
3	P23	Shadow Enable	-MCKOUT
4	P24	Output Buffer Full	KIRQ
5	P25		MIRQ
6	P26	-KCKOUT	-KCKOUT
7	P27	KDOUT	-KDOUT

Note: P22 (bit 2) is the speed control pin used by Award BIOS, and this is different from what is used by Phoenix and AMI.

**D1** Write Output Port (PC/AT and PS/2) - The next byte of data written to the keyboard data port (PORT 60H) will be written to the controller's output port. The definitions of the bits are as defined above. In PC/AT mode, P26 and P27 are not modified. In PS/2 mode, P22, P23, P26 and P27 are not modified.

**D2** Write Keyboard Output Buffer (PS/2 only) - The next byte written to the data buffer (PORT 60H) is written to the output buffer (60H) as if initiated by the keyboard [the OBF bit is set ("1") and KIRQ will be set if the EKI bit is set ("1")].

**D3** Write Mouse Output Buffer (PS/2 only) - The next byte written to the data buffer (PORT 60H) is written to the output buffer as if initiated by the mouse [the OBF bit is set ("1") and MIRQ will be set if the EMI bit is set ("1")].

**D4** Write to Mouse (PS/2 only) - The next byte written to the data buffer (PORT 60H) is transmitted to the mouse.

**E0** Read Test Inputs (PC/AT and PS/2) - This command causes the controller to read the T0 and T1 input bits. The data is placed in the output buffer with the following meanings:

Bit	PC/AT Mode	PS/2 Mode
0	Keyboard Data	Keyboard Clock
1	Keyboard Clock	Mouse Clock
3-7	Read as 0's	Read as 0's

**F0-FF** Pulse Output Port (PC/AT and PS/2) - Bits 0-3 of the controller's output port may be pulsed low for approximately 6  $\mu$ s. Bits 0-3 of the command specify which bit will be pulsed. A "0" indicates that the bit should be pulsed; a "1" indicates that the bit should not be modified. FF is treated as a special case (Pulse Null Port). In PC/AT mode, bits P26 and P27 are not pulsed. In PS/2 mode, bits P26, P27, P22 and P23 are not pulsed.

## IDE Bus Interface Control

Integrated Drive Electronics bus interface control signals are provided by the VL82C106 Combo chip. The timing and drive for these lines are consistent with the Conner Peripherals CP342 Integrated Hard Disk Manual.

A set of signals are used for this interface when the VL82C106 Combo chip is configured to support the IDE interface via IDE\_EN, bit 5 of Control Register 1 (RTC Register 6AH).

The Combo chip has duplicated bit 1 of the "Fixed Disk Register" (I/O 3F6H) to enable IRQI.

### Input Signals:

**IDINT** This signal indicates an interrupt request to the system. It is used to generate IRQI.

### Output Signals:

**-CS4** Chip Select 4. This signal is used as the floppy disk chip select. The default decode is 03F4H-03F5H, but may be redefined as described in the section on Combo Chip Control Registers. The IDE\_EN control bit of Control Register 1 has no effect on this signal. -CS4 is also active when -CDAK4 is active.

**-CS5** Chip Select 5. This signal is used as the -HOST CS0 of the IDE bus. The default decode is 01F0H-01F7H, but may be redefined as described in the section on Combo Chip Control Registers. The IDE\_EN control bit of Control Register 1 has no effect on this signal.

**-HCS1** This signal is active (low) for address 03F6H-03F7H and is used as -HOST CS1 of the IDE bus.

**-IDENH** This signal is used to drive the -OE pin of an external 74LS245 buffering bits 8-15 of the IDE data bus to the SD bus. It is active (low) when:

-CS5 is active AND SA2-SA0 = 000.

**-IDENL** This signal is used to drive the -OE pin of an external 74LS245 buffering bits 0-6 of the IDE data bus. It is active (low) when:

-CS5 is active OR SA0-SA9 = 3F6 OR 3F7.

This allows a simple implementation for an IDE bus that includes both the hard disk controller and the floppy disk controller.

**IRQI** This is the three-state interrupt request to the CPU. It is normally tied directly to the IRQ14 signal of the system. It reflects the state of the IDINT input and is enabled by writing bit 1 = 0 of I/O 3F6H as long as IDE\_EN=1. Reset or disabling the IDE system three-states IRQI.

**-IOCS16** The VL82C106 Combo chip has multiple sources for this signal. It is driven active (low) when:

(-CS5 is active AND SA0-SA2 = 000 AND IDE\_EN = 1 AND ((CS\_MODE = 0) OR (CS\_MODE = 1 AND 16-bit operation selected for CS5))) OR (any other CS is active with 16-bit operation selected AND CS\_MODE = 1) OR (IDE\_EN = 0 AND CS5 is active AND 16-bit operation is selected AND CS\_MODE = 1).

### Bidirectional Signals:

**IDB7, -DC** The control for the transceiver between IDB7, -DC, and SD7 is as follows:

IDB7 → SD7 when:

(-CS5 is active OR SA0-SA9 = 3F6) AND -IOR is active AND IDE\_EN = 1 AND NOT SA0-SA9 = 3F7H.

-DC → SD7 when SA0-SA9 = 3F7H AND -IOR is active AND IDE\_EN = 1.

SD7 → IDB7 at all other times when IDE\_EN=1, three-stated (with internal pull-up) if IDE\_EN=0.

## Combo Chip Control Ports:

Contained in the VL82C106 are a set of 26 registers used for programming peripheral chip select base addresses, chip select address ranges, and enabling options. Each base address register is a 16-bit register with bits corresponding to address bits A15-A0. In addition to base address registers, there is an address range register that can be used to "don't-care" bits (A0-A4) used in the address range comparison, effectively controlling the address space occupied by the chip select from 1 to 32 bytes. There are also programmable bits to selectively generate wait states, and assert -IOCS16 whenever the corresponding address range is present. These registers are used in groups of three per chip select, and are defined as shown below:

### Base Address Register (LSB):

Bit	Description
0	Base Address, Bit A0
1	Base Address, Bit A1
2	Base Address, Bit A2
3	Base Address, Bit A3
4	Base Address, Bit A4
5	Base Address, Bit A5
6	Base Address, Bit A6
7	Base Address, Bit A7

### Base Address Register (MSB):

Bit	Description
0	Base Address, Bit A8
1	Base Address, Bit A9
2	Base Address, Bit A10
3	Base Address, Bit A11
4	Base Address, Bit A12
5	Base Address, Bit A13
6	Base Address, Bit A14
7	Base Address, Bit A15



**Range Register:**

Bit	Description
0	Don't Care, Bit A0
1	Don't Care, Bit A1
2	Don't Care, Bit A2
3	Don't Care, Bit A3
4	Don't Care, Bit A4
5	Wait State 0
6	Wait State 1
7	8/16 Bit I/O

The only bits that need detailed descriptions are those contained in the Range Register. These bits are defined as follows:

Bits 0 to 4 - Don't Care Bits, when set ("1") causes that corresponding bit to be ignored during the chip select generation, effectively allowing the chip select signals to correspond to a range or ranges of addresses in the space from Base Address + 0 to Base Address + 31.

Bits 5 & 6 - Wait State 0 and 1, these bits determine the number of wait states that will be generated whenever the corresponding chip select signal is generated. They generate wait states according to the following table:

WS1	WS0	Wait States*
0	0	0
0	1	1
1	0	3
1	1	7

Note: Programmed wait states can only extend the I/O cycle set by the system architecture.

Bit 7 - 8/16 Bit I/O, this bit is used to selectively assert  $\text{IOCS16}$  whenever the corresponding chip select signal is generated. When set ("1"), the access is defined as an 8-bit access, and  $\text{IOCS16}$  is not asserted.

\* Number of wait states = number of  $\text{SYSCLK}$  cycles  $\text{IOCHRDY}$  is forced inactive (low) by the Combo chip.

**Default Chip Selects**

The VL82C106 Combo chip also has several hard-wired default chip selects for the serial ports, line printer port, floppy disk chip select and hard disk chip select. These default chip selects are used after a reset until the battery-backed programmable values are enabled via bit 3 of the second control register (RTC register 6AH). The wait state and non IDE  $\text{IOCS16}$  values are also disabled in this mode. This allows the Combo chip to function normally without the need for programming. The default chip selects are:

Select/Device	Address
COMA	3F8H-3FFH (Bit 3 of RTC Reg 69H = 1) 2F8H-2FFH (Bit 3 of RTC Reg 69H = 0)
COMB	2F8H-2FFH (Bit 3 of RTC Reg 69H = 1) 3F8H-3FFH (Bit 3 of RTC Reg 69H = 0)
LPT	03BCH-03BFH (Bit 5, 6 of RTC Reg 69H = 0, 0) 0378H-037BH (Bit 5, 6 of RTC Reg 69H = 1, 0) 0278H-027BH (Bit 5, 6 of RTC Reg 69H = 0, 1)
-CS4	03F4H-03F5H
-CS5	01F0H-01F7H
-CS6	03F2H AND $\text{IOW}$ is Active
-CS7	03F7H AND $\text{IOW}$ is Active

Note: Note that on reset, COMA, COMB, LPT, and  $\text{CS4}$  through  $\text{CS7}$  are enabled and set to the hard-wired values.  $\text{CS6}$  and  $\text{CS7}$  are only qualified by  $\text{IOW}$  when the hard-wired decodes are enabled. By writing values to control registers 7Ah through 7Fh and enabling these values via bit 3 of Control Register 1, the  $\text{IOW}$  qualification is removed.  $\text{CS6}$  and  $\text{CS7}$  then become general purpose chip selects usable for read and write cycles.

Addr	Usage
69	Control Register 0*
6A	Control Register 1*
6B	CS1 COMA Base Add LSB
6C	CS1 COMA Base Add MSB
6D	CS1 COMA Range
6E	CS2 COMB Base Add LSB
6F	CS2 COMB Base Add MSB
70	CS2 COMB Range
71	CS3 LPT Base Add LSB
72	CS3 LPT Base Add MSB
73	CS3 LPT Range
74	CS4 FDC Base Add LSB
75	CS4 FDC Base Add MSB
76	CS4 FDC Range
77	CS5 HDC Base Add LSB
78	CS5 HDC Base Add MSB
79	CS5 HDC Range
7A	CS6 Base Add LSB
7B	CS6 Base Add MSB
7C	CS6 Range
7D	CS7 Base Add LSB
7E	CS7 Base Add MSB
7F	CS7 Range

**Combo Chip Control Register**

The VL82C106 Combo chip contains a number of programmable options, including peripheral base address and chip select "hole" size. The registers used to provide this control are located in the upper bytes of the RTC address space. They are defined as follows:

\* Note: Control Register 0 and 1 are not battery-backed via the  $\text{VBAT}$  supply.

This register can also be accessed at address 102H, for PS/2 compatibility. The contents of the register are detailed below:

Bit	Usage	Value After Reset
0	SYS BD EN	Enabled (1)
1	FDCS EN (CS4)	Enabled (1)
2	COMA EN (CS1)	Enabled (1)
3	COMA DEF	COM1 (1)
4	LPT EN (CS3)	Enabled (1)
5	LPT DEF 0	Paralled Port 1 (0)
6	LPT DEF 1	Disabled (0)
7	-EMODE	Compat. Mode (1)

**Bit 0 - System Board Enable (SYS BD EN) Control bit**, when set ("1") allows bits 1, 2, and 4 to enable and disable their respective devices. When reset ("0") the floppy disk chip select (CS4), COMA (CS1), and the LPT port (CS3) are disabled regardless of the contents of bits 1, 2, and 4.

**Bit 1 - Floppy Disk CS Enable (FDCS EN) Control bit**, when set ("1") allows the FD CS signal (CS4) to be asserted to an external floppy disk controller chip. When reset ("0") prevents the assertion of this chip select.

**Bit 2 - Communications Port A Enable (COMA EN) Control bit**, when set ("1") allows the internal COMA (CS1) port to be accessed. When reset ("0") COMA is disabled.

**Bit 3 - Communications Port A Default Address (COMA DEF) Control bit**, when set ("1") forces the hard-wired default base address to COMA to correspond to (3F8H-3FFH) and COMB to (2F8H-2FFH). When reset ("0") forces the COMA hard-wired address to (2F8H-2FFH) and COMB to (3F8H-3FFH). The base address will be the programmed values if bit 3 of control register 1 (RTC register 6AH) is set.

**Bit 4 - Line Printer Port Enable (LPT EN) Control bit**, when set ("1") enables the LPT port (CS3). When reset ("0") disables the LPT port.

**Bit 5 & 6 - Line Printer Default bits 0 and 1 (LPT DEF 0 and 1) Control bits**, set the Line Printer Base hard-wired address defaults as shown below:

Bit 6	Bit 5	Address Range
0	0	03BCH-03BFH
0	1	0378H-037BH
1	0	0278H-027BH
1	1	Reserved

Setting bit 3 of RTC register 6AH changes the base address to that set in the program address registers for LPT (CS3).

**Bit 7 - Line Printer Extended Mode (EMODE) Control bit**, when set ("1") disables the Extended Mode and forces PC/AT compatibility. When reset ("0"), the Extended Mode is enabled, allowing the printer port direction to be controlled.

#### Control Register 1 (RTC Register 6AH) Bits

This register is used to control peripheral chip selects that are not included in Control Register 0. The bits in this register are defined as follows:

Bit	Usage	Value After Reset
0	COMB EN	Enabled (1)
1	AT/PS2 KBD	AT (1)
2	PRIV EN	Enabled (1)
3	CS MODE	Hard-wire (0)
4	HDCS EN	Enabled (1)
5	IDE EN	Enabled (1)
6	CS6 EN	Enabled (1)
7	CS7 EN	Enabled (1)

**Bit 0 - Communication Port B Enable.** A "1" enables COMB (CS2). A zero ("0") disables COMB.

**Bit 1 - AT or PS/2 Compatible Keyboard.** A "1" selects PC/AT type keyboard controller functions, while a "0" places the keyboard controller in PS/2 mode.

**Bit 2 - Private Controls Enable.** When in AT mode (AT/PS2\_KBD = 1), this bit is used to latch the values of the keyboard controller's output signals KHSE, KSRE, and IRQM to the VL82C106 output pins. When "1", these outputs follow the keyboard controller's outputs. When "0", these outputs held at that value regardless of the keyboard controller's outputs.

When in PS/2 mode (AT/PS2\_KBD = 0), this bit has no effect on the KHSE, KSRE, and IRQM output pins. The Combo chip outputs follow the keyboard controller's outputs.

**Bit 3 - Chip Select Decode Mode.** When "0", CS1-CS7 decodes revert to the hard-wired address decoding and non IDE -IOCS16 and IOCHRDY generation is disabled. A "1" enables the address decoding, wait state generation and 8/16-bit operation as programmed into the RTC registers 69H-7FH. (See sections on Default Chip Selects and Combo Chip Control Register.)

**Bit 4 - Hard Disk Chip Select Enable.** A "1" enables the Hard Disk Chip Select signal (-CS5), while a "0" disables the chip select.

**Bit 5 - Integrated Drive Electronics Enable.** A "1" enables the IDE functions of outputs -IDENH, -IDENL, IRQI, -IOCS16, and IDB7 as described in IDE Bus Interface Control section.

**Bit 6 - Chip Select 6 Enable.** When "0", the -CS6 output is disabled. A "1" enables the address decoding, wait state generation and 8/16-bit operation as programmed into the RTC registers 7A-7CH. (See sections on Default Chip Selects and Combo Chip Control Registers.)

**Bit 7 - Chip Select 7 Enable.** When "0", the -CS7 output is disabled. A "1" enables the address decoding, wait state generation and 8/16-bit operation as programmed into the RTC registers 7D-7FH. (See sections Default Chip Selects and Combo Chip Control Register.)



**Miscellaneous Control Signals**

<p>XDDIR</p>	<p>This input signal is normally generated by the system. It is inactive (low) when data is transferred from the XD bus to the SD bus, i.e., interrupt acknowledge cycles and I/O read accesses to addresses 000H-0FFH.</p>	<p>-CDAK4</p>	<p>This input will directly produce an active low on -CS4 when active low itself and is used by the IDE logic.</p>	<p>Note:</p>	<p>Programmed wait states can only extend the I/O cycle, i.e., if the system architecture provides four wait states for 8-bit I/O, programming 1 or 3 has no effect.</p>
<p>XDIRS</p>	<p>This output signal is to control the direction pin of a transceiver between the XD bus and the SD bus when the Combo chip is on the SD bus. Since the architecture assumes the RTC and Keyboard Controller are on the XD bus, this signal is set active (high) when XDDIR is high or either the RTC or the Keyboard Controller is selected.</p>	<p>-IOCS16</p>	<p>This output signal is used to indicate to the system that the peripheral being accessed is a 16-bit device. It is set active (low) when a programmed chip select, which specifies 16-bit I/O, is decoded or for certain IDE functions. (See sections on Combo Chip Control Ports and IDE Bus Interface Control.)</p> <p>When 16-bit programmed chip select operation is selected, -IOCS16 becomes active on the leading edge of ALE and inactive on the trailing edge of -IOW or -IOR. For 8-bit operation or default chip select operation, -IOCS16 is inactive during -IOW or -IOR active.</p>	<p>XTAL1</p>	<p>This pin is the input to the on-board 18.432 MHz crystal oscillator. This pin may also be driven by an external CMOS clock signal at 18.432 MHz.</p>
<p>XDIRX</p>	<p>This output signal is to control the direction pin of the transceiver between the XD bus and the SD bus when the Combo chip is on the XD bus. Since the architecture assumes the peripherals other than the RTC and Keyboard Controller are on the SD bus, this signal is inactive (low) when the XDDIR is low or when -IOR is low and any chip select (CS1-CS7) is generated.</p>	<p>IOCHRDY</p>	<p>This output signal is used to the lengthen I/O cycle to the peripheral being accessed. It is set inactive (low) for the programmed number of wait states when a programmed chip select, which specifies one, three, or seven wait states, is decoded. (See the section IDE Bus Interface Control.) IOCHRDY transitions inactive at the falling edge of -IOW or -IOW, if enabled, and returns high at the falling edge of SYSCLK after the appropriate number of wait states (SYSCLK cycles).</p>	<p>XTAL2</p>	<p>This pin is the output pin of the internal crystal oscillator and should be left open and unloaded if an external clock signal is applied to the XTAL1 pin. This pin is not capable of driving external loads other than the crystal.</p>
<p>-XDEN</p>	<p>This output signal is used to enable the XD bus transceiver when the VL82C106 Combo chip is placed on the XD bus and DMA's are desired for peripherals controlled by the Combo chip selects. It is the AND of -IOR and -IOW (active low when either -IOR or -IOW are active).</p>			<p>-TRI</p>	<p>This pin is used for in-circuit testing. When low, all outputs and I/O pins are placed in the high impedance state.</p>
				<p>-ICT</p>	<p>This pin, when strobed low, places the VL82C106 into test mode, determined by the data on the SD0 through SD3 pins. The chip will remain in this mode until RES is asserted. Test mode may be changed by strobing this pin low again with different data on the SD0-SD3 pins.</p>



**AC CHARACTERISTICS: TA = 0°C to +70°C, VCC = 5 V ±5%, GND = 0 V**

Symbol	Parameter	Min	Max	Unit	Conditions
<b>I/O Read/Write Figures 6, 7</b>					
tSU1	Address Setup Time	55		ns	
tH2	Address Hold Time	20		ns	
tSU3	AEN Setup Time	55		ns	
tH4	AEN Hold Time	20		ns	
t5	Command Pulse Width	125		ns	
tSU6	Write Data Setup	60		ns	
tH7	Write Data Hold	20		ns	
tD8	Read Data Delay	0	130	ns	CL=200 pF
tH9	Read Data Hold	5	60	ns	CL=50 pF
WC	Write Cycle	280		ns	
RC	Read Cycle	280		ns	

**Chip Select Timing (Hard-wired) Figures 8, 10**

tD11	Chip Select Delay from Address		35	ns	CL=50 pF
tD12	-CS6, -CS7 Delay from -IOW		30	ns	CL=50 pF
tD13	-IOCS16 Active from Address		60	ns	CL=200 pF
tD14	-CS4 Delay from -CDAK4		25	ns	CL=50 pF

**Chip Select Timing (Programmable) Figures 8, 10**

tD11	Chip Select Delay from Address		45	ns	CL=50 pF
tD13	-IOCS16 Active from Address		70	ns	CL=200 pF
tD14	-CS4 Delay from -CDAK4		25	ns	CL=50 pF

**-IOCS16/IOCHRDY Timing Figures 9, 10**

tD15	IOCHRDY Inactive from Command		50	ns	CL=200 pF
tD16	IOCHRDY Active from SYSCLK		55	ns	CL=200 pF
tD17	-IOCS16 Inactive from Command		55	ns	CL=200 pF

**SYSCLK/ALE Timing Figures 9, 10**

t18	SYSCLK Period	84		ns	
t19	SYSCLK Pulse Width Low	35		ns	
t20	SYSCLK Pulse Width High	35		ns	
t21	ALE Pulse Width High	40		ns	

**Note:** -IOCS16, IOCHRDY are open-drain outputs with an active pull-up for approximately 10 ns. These parameters are measured at V<sub>OH</sub> = 1.5 V with a 300 ohm pull-up. Actual performance will vary depending on system configuration.

**AC CHARACTERISTICS (Cont.):** TA = 0°C to +70°C, VCC = 5 V ±5%, VSS = 0 V

Symbol	Parameter	Min	Max	Unit	Conditions
<b>IDE Interface Timing Figure 11</b>					
tD18	IRQI Delay from IDINT		40	ns	CL=100 pF
tD19	IDENH/IDENL Delay from Address		60	ns	CL=50 pF
tD20	IDB7 Delay from SD7 Input		40	ns	CL=200 pF
tD21	SD7 Delay from IDB7 Input		40	ns	CL=200 pF
tD22	SD7 Delay from -DC Input		40	ns	CL=200 pF
tD23	SD7 Delay from -IOR During IDE Access	0	85	ns	CL=200 pF
tH24	SD7 Hold from -IOR Inactive	5	60	ns	CL=50 pF
tD25	IDB7 Delay from -IOR Inactive	0	85	ns	CL=200 pF
tH26	IDB7 Hold from -IOR Active	5	60	ns	CL=50 pF
<b>XDATA Control Timing Figure 12</b>					
tD27	-XDIRS/-XDIRX Delay from -XDDIR		30	ns	CL=50 pF
tD28	-XDIRX Delay from -IOR		30	ns	CL=50 pF
tD29	-XDEN Delay from Command		30	ns	CL=50 pF
<b>Real Time Clock Timing Figure 18</b>					
tPSPW	Power Sense Pulse Width	2		μs	
tPSD	Power Sense Delay	2		μs	
tVRTD	VRT Bit Delay		2	μs	
tSBPW	-STBY Pulse Width	2		μs	

**AC CHARACTERISTICS (Cont.): TA = 0°C to +70°C, VCC = 5 V ±5%, GND = 0 V**

Symbol	Parameter	Min	Max	Units	Conditions
--------	-----------	-----	-----	-------	------------

**SERIAL, PRINTER**
**Transmitter Figure 13**

tHR1	Delay from Rising Edge of $\text{-IOW}$ (WR THR) To Reset Interrupt		175	ns	100 pF Load
tIRS	Delay from THRE Reset to Transmit Start		16	CLK Cycles	Note 2
tSI	Delay from Write to THRE	8	24	CLK Cycles	Note 2
tSTI	Delay from Stop to Interrupt (THRE)		8	CLK Cycles	Note 2
tIR	Delay from $\text{-IOR}$ (RD IIR) to Reset Interrupt (THRE)		250	ns	100 pF Load

**Modem Control Figure 14**

tMDO	Delay from $\text{-IOW}$ (WR MCR) to Output		250	ns	100 pF Load
tSIM	Delay to Set Interrupt from MODEM Input		250	ns	100 pF Load
tRIM	Delay to Reset Interrupt from $\text{-IOR}$ (RS MSR)		250	ns	100 pF Load

**Receiver Figure 12**

tSINT	Delay from Stop to Set Interrupt		1	CLK Cycles	Note 2
tRINT	Delay from $\text{-IOR}$ (RD RBR/RDLSR) to Reset Interrupt		1	$\mu\text{s}$	100 pF Load

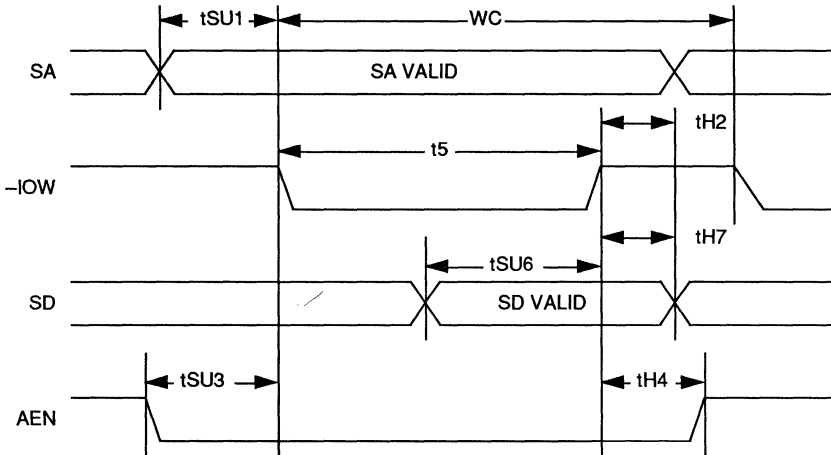
**Parallel Port Figure 15**

tDT	Data Time	1		$\mu\text{s}$	Software Controller
tSB	Strobe Time	1	500	$\mu\text{s}$	Software Controller
tAD	Acknowledge Delay (Busy Start to Acknowledge)			$\mu\text{s}$	Defined by Printer
tAKD	Acknowledge Delay (Busy End to Acknowledge)			$\mu\text{s}$	Defined by Printer
tAK	Acknowledge Duration Time			$\mu\text{s}$	Defined by Printer
tBSY	Busy Duration Time			$\mu\text{s}$	Defined by Printer
tBSD	Busy Delay Time			$\mu\text{s}$	Defined by Printer

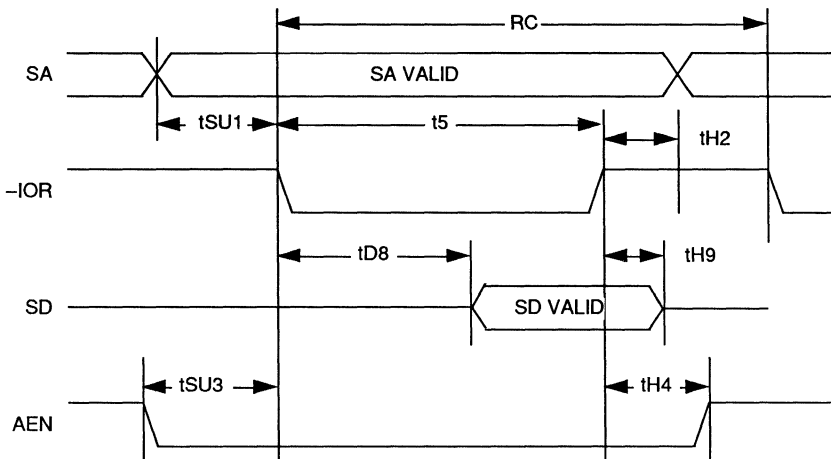
- Notes:**
1. All timing specifications apply to pins on both serial channels (e.g. RI refers to both RI0 and RI1).
  2. CLK cycle refers to external 18.432 MHz clock divided by 10, e.g. 1.8432 MHz.

**BUS TIMING**

**FIGURE 6. WRITE CYCLE**

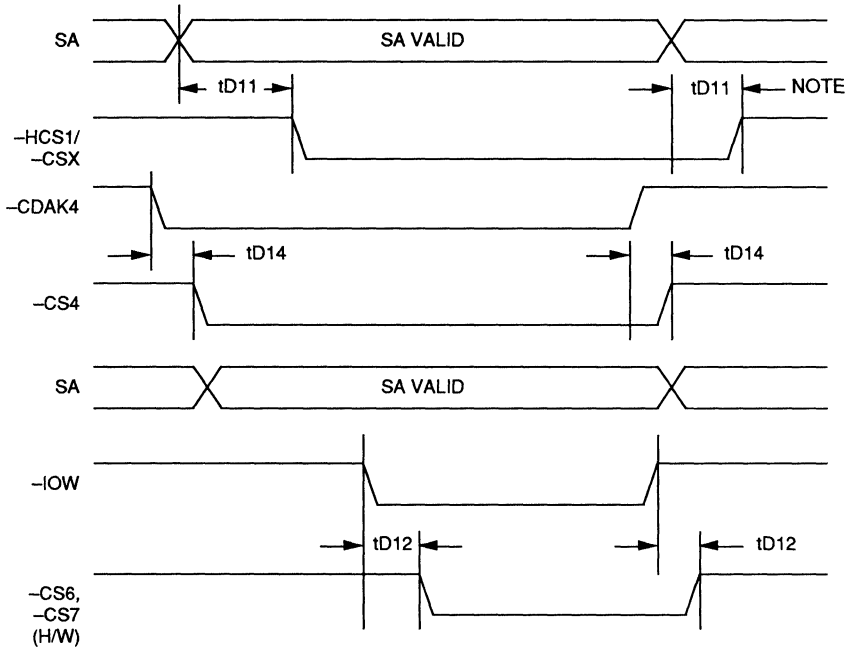


**FIGURE 7. READ CYCLE**



CHIP SELECT TIMING

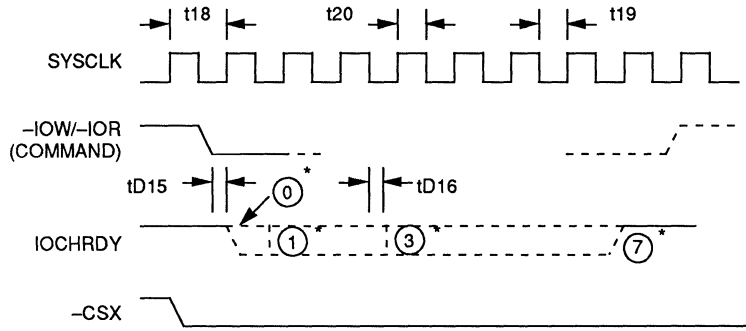
FIGURE 8.



Note: Except -CS6, -CS7 hard-wired.

**IOCHRDY TIMING**

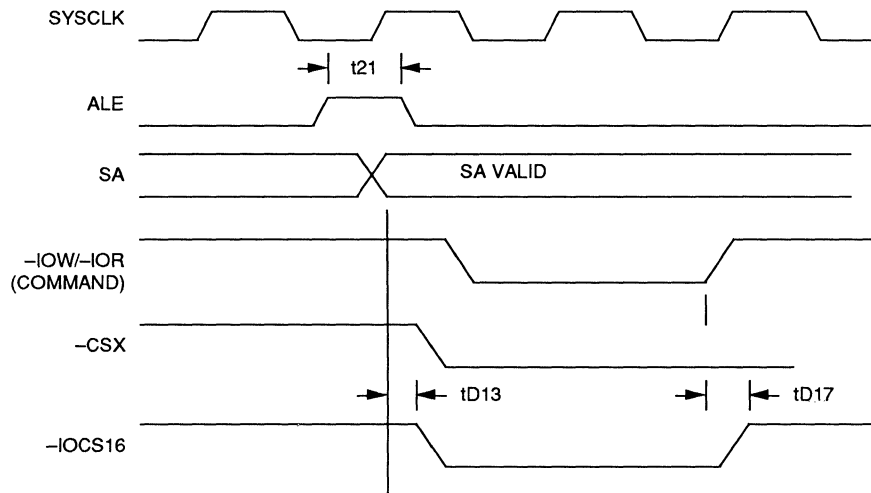
FIGURE 9.



\* Programmed number of wait states. 0 = 0 wait state, 1 = 1 wait states, etc.

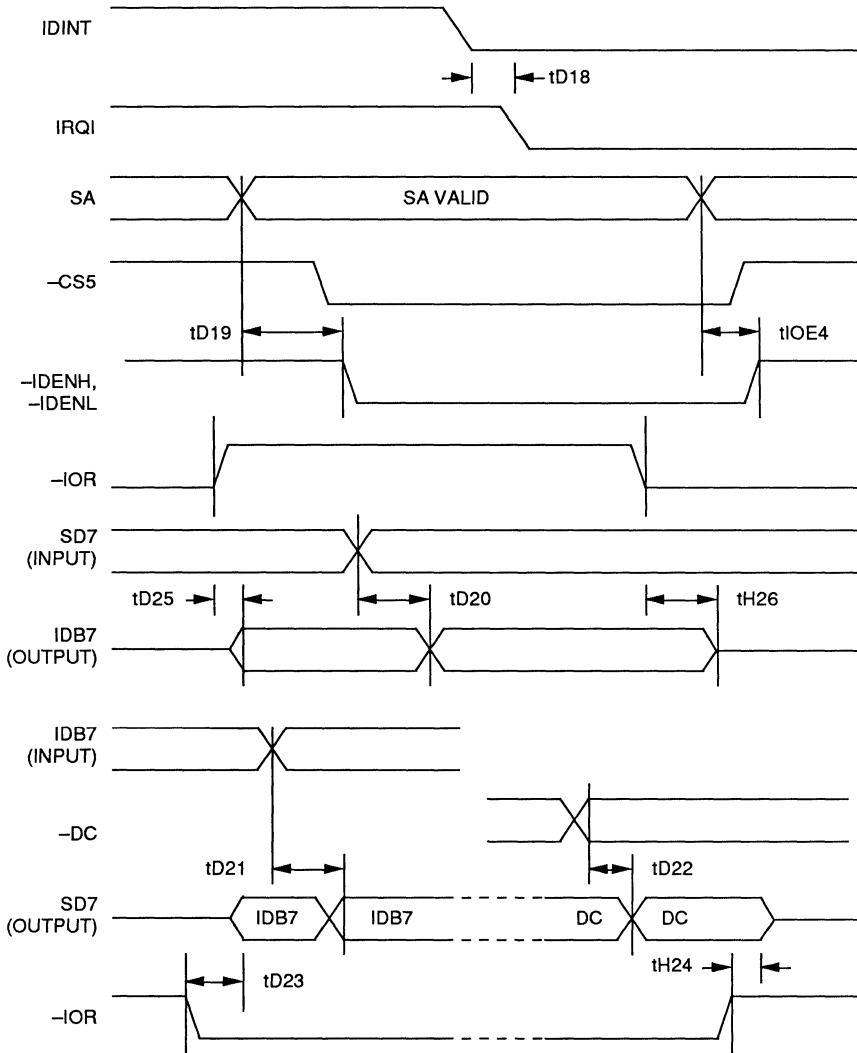
**IOCS16 TIMING**

FIGURE 10.



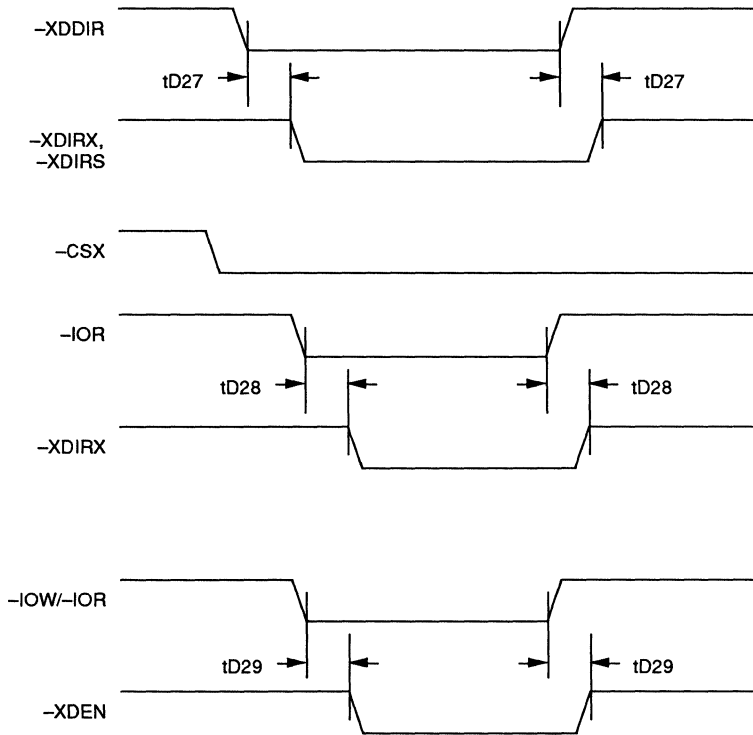
IDE INTERFACE TIMING

FIGURE 11.



XDATA CONTROL TIMING

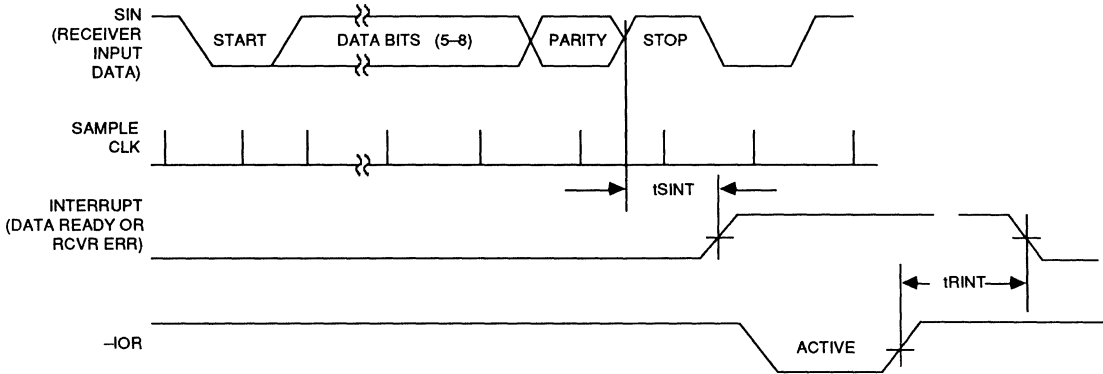
FIGURE 12.





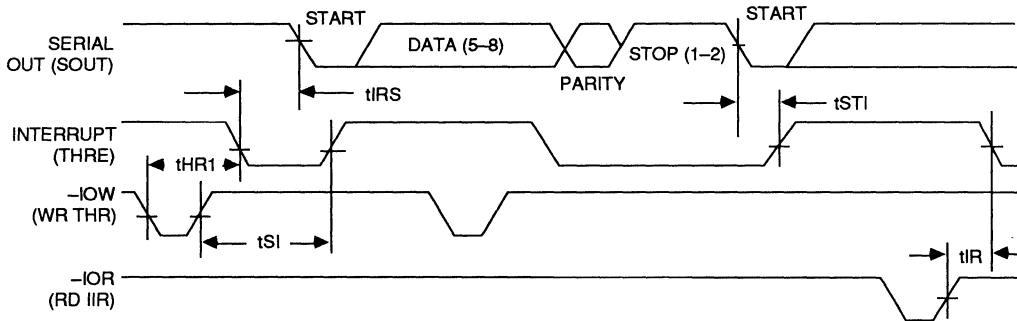
**RECEIVER TIMING**

FIGURE 13.



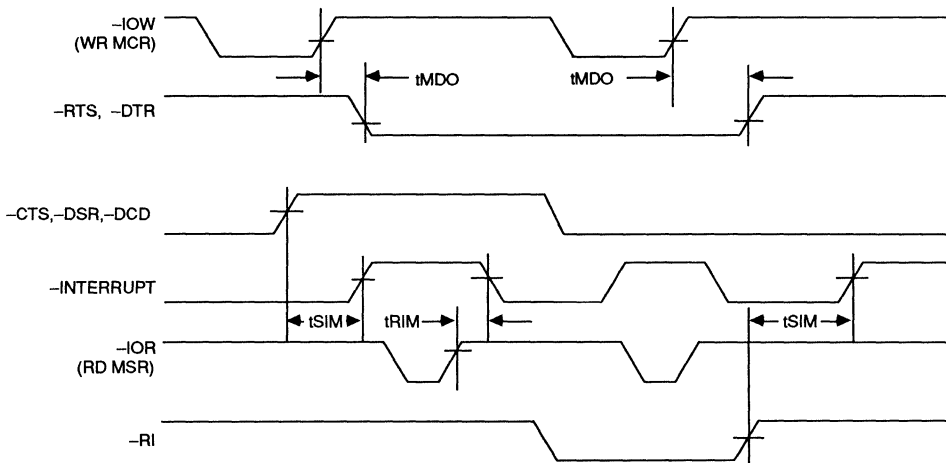
**TRANSMITTER TIMING**

FIGURE 14.



**MODEM TIMING**

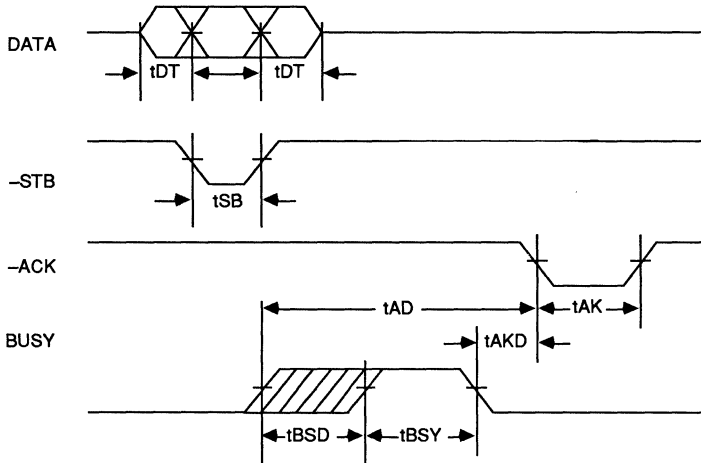
FIGURE 15.





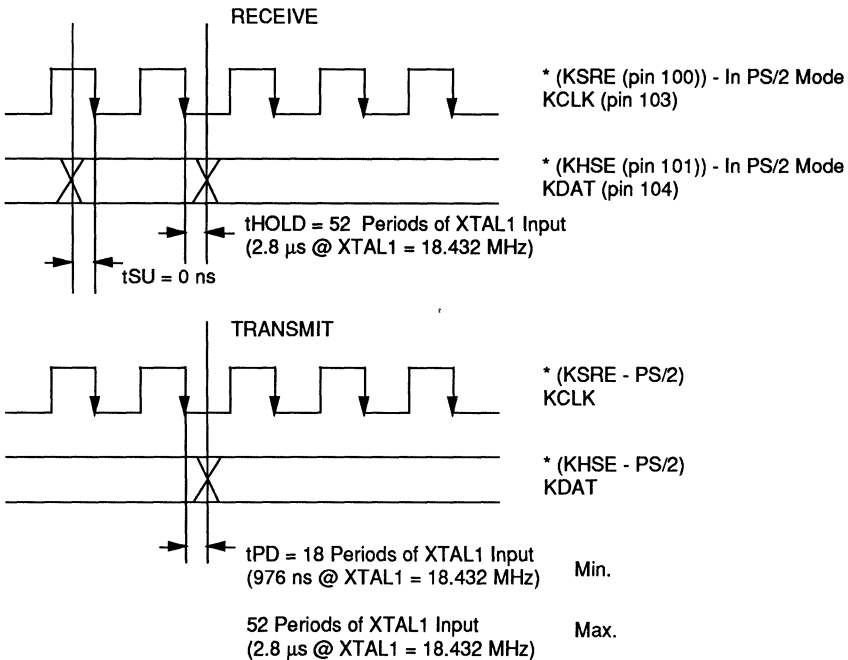
**PARALLEL PORT TIMING**

FIGURE 16.



**KEYBOARD CONTROLLER TIMING**

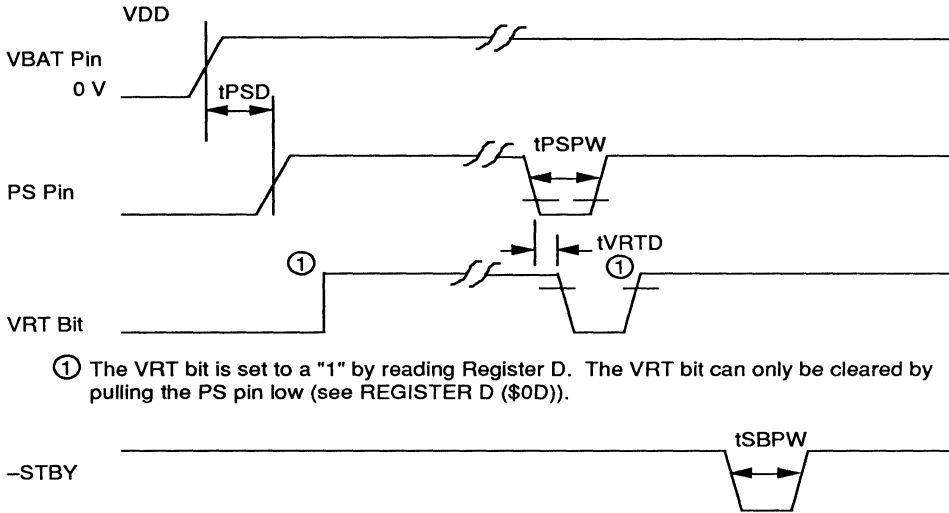
FIGURE 17.



\* Note: Specifications are identical for KHSE (pin 101) with respect to KSRE (pin 100) in PS/2 Mode.

**REAL TIME CLOCK TIMING**

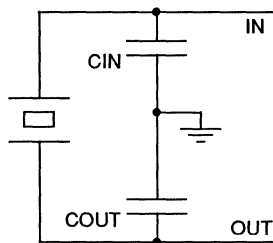
FIGURE 18.



① The VRT bit is set to a "1" by reading Register D. The VRT bit can only be cleared by pulling the PS pin low (see REGISTER D (\$0D)).

**CRYSTAL OSCILLATOR CONFIGURATIONS**

FIGURE 19.



6

**32.768 KHz**

$C_{IN} = C_{OUT} = 10-22 \text{ pF}$   
 $C_{IN}$  may be a trimmer for precision timekeeping applications.

**18.432 MHz**

$C_{IN} = 10 \text{ pF}$   
 $C_{OUT} = 30 \text{ pF}$

**RECOMMENDED CRYSTAL PARAMETERS**

$R_s (\text{max}) \leq 40k \Omega$   
 $C_o (\text{max}) \leq 1.7 \text{ pF}$   
 $C_l (\text{max}) \leq 12.5 \text{ pF}$   
 Parallel Resonance

$R_s \leq 50 \Omega$   
 $C_o \leq 7 \text{ pF}$   
 $C_l \leq 20 \text{ pF}$   
 Parallel Resonance



**ABSOLUTE MAXIMUM RATING**

Ambient Temperature -10°C to +70°C  
 Storage Temperature -65°C to 150°C  
 Supply Voltage to Ground Potential -0.5 V to VDD +0.3 V  
 Applied Output Voltage -0.5 V to VDD +0.3 V  
 Applied Input Voltage -0.5 V to +7.0 V  
 Power Dissipation 500 mW

Stresses above those listed may cause permanent damage to the device. These are stress ratings only. Functional operation of this device at these or any other conditions above those

indicated in this data sheet is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**DC CHARACTERISTICS: TA = 0°C to +70°C, VDD = 5 V ±5%, VSS = 0 V**

Symbol	Parameter	Min	Max	Units	Conditions
VIL	Input Low Voltage	-0.5	0.8	V	
	Input Types (All except I2) Input Type I2	-0.5	VDD*0.2	V	
VIH	Input High Voltage	2.0	VDD+0.5	V	
	Input Types I1, I3, I4, IO2, IO4, IO5, IO6	VDD*0.7	VDD+0.5	V	
	Input Type I2 Input Type I5	2.4	VDD+0.5	V	
VOL	Output Low Voltage		0.4	V	IOL = 2.0 mA
	Output Type O1		0.4	V	IOL = 4.0 mA
	Output Type O6		0.4	V	IOL = 12.0 mA
	Output Type O4, IO4, IO5 Output Type O2, O7, O8, IO2, IO6		0.4	V	IOL = 24.0 mA
VOH	Output High Voltage	2.4		V	IOH = -0.8 mA
	Output Type O1, O6	2.4		V	IOH = -2.0 mA
	Output Type IO5 Output Type O2, IO2, IO6	2.4		V	IOH = -2.4 mA
IIH	Input High Current Input Types I1, I3, I4, I5		10	µA	VIN = VDD
IIL	Input Low Current	-10		µA	VIN = VSS + 0.2
	Input Types I1, I5 Input Types I4, IO6	-500	-50	µA	VIN = 0.8 V All other pins floating.
ILOL	Three-State Leakage Current	-50		µA	VSS+0.2
	I/O Output Types O6, O7, IO2, IO4, IO5		50	µA	VDD
IODL	Open-Drain Off Current I/O Output Type O4	-5.0	-1.0	mA	V = 0.8 V
CO	Output Capacitance		8	pF	
CI	Input		8	pF	
CIO	Input/Output Capacitance		16	pF	
IDD	Operating Supply Current		40	mA	
IBAT	VBAT Supply Current, Standby Mode		5.0	µA	VBAT = 3.0 V
			50.0	µA	VBAT = 5.0 V

**Note:** For pin types, refer to the Legend and Pin Descriptions on pages 188-191 of this data sheet.